## Math 4073: Polynomial Lagrange Interpolation

Interpolation is the filling-in of missing data; from just a few samples of an otherwise unknown function we try to reconstruct that unknown function. In some sense this must be impossible but nevertheless we can do very well in practice! We start by looking at the Lagrange interpolating polynomial. ${ }^{1}$


Setup and notation Let $\Pi_{n}=\{$ real polynomials of degree $\leq n\}$. Problem: given scalar data $f_{i}$ at distinct scalar $x_{i}, i=0,1, \ldots, n$, with $x_{0}<x_{1}<\cdots<x_{n}$, can we find a polynomial $p_{n}$ such that $p_{n}\left(x_{i}\right)=f_{i}$ ? Such a polynomial is said to interpolate the data.
Theorem: $\exists p_{n} \in \Pi_{n}$ such that $p_{n}\left(x_{i}\right)=f_{i}$ for $i=0,1, \ldots, n$.
Proof (Constructive!) Consider, for $k=0,1, \ldots, n$, the "cardinal polynomial"

$$
\begin{equation*}
L_{n, k}(x)=\frac{\left(x-x_{0}\right) \cdots\left(x-x_{k-1}\right)\left(x-x_{k+1}\right) \cdots\left(x-x_{n}\right)}{\left(x_{k}-x_{0}\right) \cdots\left(x_{k}-x_{k-1}\right)\left(x_{k}-x_{k+1}\right) \cdots\left(x_{k}-x_{n}\right)} \in \Pi_{n} . \tag{1}
\end{equation*}
$$

Then $L_{n, k}\left(x_{i}\right)=0$ for $i=0, \ldots, k-1, k+1, \ldots, n$ and $L_{n, k}\left(x_{k}\right)=1$. Now define

$$
\begin{equation*}
p_{n}(x)=\sum_{k=0}^{n} f_{k} L_{n, k}(x) \in \Pi_{n} . \tag{2}
\end{equation*}
$$

Now this implies that

$$
p_{n}\left(x_{i}\right)=\sum_{k=0}^{n} f_{k} L_{n, k}\left(x_{i}\right)=f_{i}, \quad \text { for } \quad i=0,1, \ldots, n
$$

The polynomial (2) is the Lagrange interpolating polynomial. The cardinal polynomials for $n=3$ look like:





Theorem: The interpolating polynomial of degree $\leq n$ (through $n+1$ points) is unique.
Proof "One root too many". Consider two interpolating polynomials $p_{n}, q_{n} \in \Pi_{n}$. Difference $d_{n}=$ $p_{n}-q_{n} \in \Pi_{n}$ satisfies $d_{n}\left(x_{k}\right)=0$ for $k=0,1, \ldots, n$, i.e., $d_{n}$ is a polynomial of degree at most $n$ but has at least $n+1$ distinct roots. Fundamemtal Theorem of Algebra $\Longrightarrow d_{n} \equiv 0 \Longrightarrow p_{n}=q_{n}$.
Demos: demo_03_lagrange.m and demo_03_lagrange_construct.m.
Data from a smooth function Suppose that $f(x)$ has at least $n+1$ smooth derivatives in the interval $\left(x_{0}, x_{n}\right)$. Let $f_{k}=f\left(x_{k}\right)$ for $k=0,1, \ldots, n$, and let $p_{n}$ be the Lagrange interpolating polynomial for the data $\left(x_{k}, f_{k}\right), k=0,1, \ldots, n$.
Error: how large can the error $f(x)-p_{n}(x)$ be on the interval $\left[x_{0}, x_{n}\right]$ ?
Theorem: For every $x \in\left[x_{0}, x_{n}\right]$ there exists $\xi=\xi(x) \in\left(x_{0}, x_{n}\right)$ such that

$$
e(x):=f(x)-p_{n}(x)=\left(x-x_{0}\right)\left(x-x_{1}\right) \cdots\left(x-x_{n}\right) \frac{f^{(n+1)}(\xi)}{(n+1)!},
$$

where $f^{(n+1)}$ is the $(n+1)$-st derivative of $f$.
Proof (sketch) Trivial for $x=x_{k}, k=0,1, \ldots, n$ because $e(x)=0$ by construction. So suppose $x \neq x_{k}$. Key idea is to define

$$
\phi(t):=e(t)-\frac{e(x)}{\pi(x)} \pi(t),
$$

[^0]where $\pi(t):=\left(t-x_{0}\right)\left(t-x_{1}\right) \cdots\left(t-x_{n}\right)=t^{n+1}+\cdots \in \Pi_{n+1}$. Now count at how many points $\phi$ vanishes. Note $\phi^{\prime}$ must vanish at one fewer points. Continue recursively until there is only a single root.
Error for equispaced points Common in practice to want to use an equispaced grid with spacing $h=\frac{x_{n}-x_{0}}{n}$. In this case the error formula becomes
$$
\left|f(x)-p_{n}(x)\right| \leq \frac{h^{n+1}}{4(n+1)} \max _{\xi \in\left[x_{0}, x_{n}\right]} f^{(n+1)}(\xi) .
$$

But be careful! There are two terms there: how do they balance as $n$ gets large?
Runge phenomenon Famous example due to Carl Runge (1901); the error from the interpolating polynomial approx. to $f(x)=\left(1+x^{2}\right)^{-1}$ for $n+1$ equally-spaced points on $[-5,5]$ diverges near $\pm 5$ as $n$ tends to infinity: try demo_03_runge.m.
Practical advice So polynomial interpolation in a large number of equispaced points is a bad idea! Exception: periodic functions. Instead, if you can control the grid, use special "clustered" points such as Chebyshev points (see Runge demo and "Chebfun" software). Or use smaller number of points ( $n \leq 8$ ), in a local piecewise fashion: e.g., interp in MATLAB/Octave, also "splines".
For uniform grids of samples (e.g., from meshgrid), polynomial interpolation can be applied in a dimension-by-dimension fashion (interp2/interp3). For scattered data, see e.g., Radial Basis Functions.
Computer implementation The Barycentric Formula for Lagrange Interpolation gives a more stable and cheaper way of implementing interpolation (compared to working with the cardinal polynomials directly):

$$
\begin{equation*}
p_{n}(x)=\frac{\sum_{k=0}^{n} \frac{w_{k}}{\left(x-x_{k}\right)} f\left(x_{k}\right)}{\sum_{k=0}^{n} \frac{w_{k}}{\left(x-x_{k}\right)}} \tag{3}
\end{equation*}
$$

where $w_{k}=\frac{1}{\left(x_{k}-x_{0}\right) \ldots\left(x_{k}-x_{k-1}\right)\left(x_{k}-x_{k+1}\right) \ldots\left(x_{k}-x_{n}\right)}$. Note: can still suffer from Runge phenomenon.

## Building Lagrange interpolating polynomials from lower degree ones

Notation: let $Q_{i, j}$ be the interpolating polynomial at $x_{k}, k=i, \ldots, j$.
Theorem:

$$
\begin{equation*}
Q_{i, j}(x)=\frac{\left(x-x_{i}\right) Q_{i+1, j}(x)-\left(x-x_{j}\right) Q_{i, j-1}(x)}{x_{j}-x_{i}} \tag{4}
\end{equation*}
$$

Proof: Let $s(x)$ denote the right-hand side of (4). Because of uniqueness, we wish to show that $s\left(x_{k}\right)=f_{k}$ and that the $s(x)$ is of the correct degree; left as exercises.
This can be used as the basis for constructing interpolating polynomials. In many textbooks (e.g., Burden and Faires) you'll find topics such as the Newton form and divided differences.

Generalization: Hermite interpolation Given data $f_{i}$ and $g_{i}$ at distinct $x_{i}, i=0,1, \ldots, n$, with $x_{0}<x_{1}<\cdots<x_{n}$, can we find a polynomial $p$ such that $p\left(x_{i}\right)=f_{i}$ and $p^{\prime}\left(x_{i}\right)=g_{i}$ ? Yes, there is such a unique polynomial $p_{2 n+1} \in \Pi_{2 n+1}$ :
Construction: given $L_{n, k}(x)$ in (1), let $H_{n, k}(x)=\left[L_{n, k}(x)\right]^{2}\left(1-2\left(x-x_{k}\right) L_{n, k}^{\prime}\left(x_{k}\right)\right)$ and $K_{n, k}(x)=$ $\left[L_{n, k}(x)\right]^{2}\left(x-x_{k}\right)$. Then the Hermite interpolating polynomial

$$
\begin{equation*}
p_{2 n+1}(x)=\sum_{k=0}^{n}\left[f_{k} H_{n, k}(x)+g_{k} K_{n, k}(x)\right] \tag{5}
\end{equation*}
$$

interpolates the data as required.
What's next? We can use $p_{n}(x)$ as a proxy for the (unknown) $f(x)$ : numerical integration/differentiation.


[^0]:    ${ }^{1}$ Some material adapted from Ch. 6 of the numerical analysis textbook by Süli and Mayers.

