

Solutions to H.W. 10

Section 4.6 :

(13) $W = \text{Span}\{ \underset{v_1}{t^3+t^2-2t+1}, \underset{v_2}{t^2+1}, \underset{v_3}{t^3-2t}, \underset{v_4}{2t^3+2t^2-4t+3} \}$

$$a_1 v_1 + a_2 v_2 + a_3 v_3 + a_4 v_4 = 0 \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 2 & | & 0 \\ 1 & 1 & 0 & 2 & | & 0 \\ -2 & 0 & -2 & -4 & | & 0 \\ 1 & 1 & 0 & 3 & | & 0 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 0 & 1 & 2 & | & 0 \\ 0 & 1 & -1 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$

Leading 1's give us
 \Rightarrow Basis = $\{v_1, v_2, v_4\}$

(16) $W =$ symmetric matrixes in M_{33}

$$A = \begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix} = a \underset{v_1}{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}} + b \underset{v_2}{\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}} + c \underset{v_3}{\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}} + d \underset{v_4}{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}} + e \underset{v_5}{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}} + f \underset{v_6}{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}}$$

$\Rightarrow W = \text{Span}\{v_1, v_2, v_3, v_4, v_5, v_6\}$

Check that these vectors are lin. ind. \Rightarrow Basis for $W = \{v_1, v_2, v_3, v_4, v_5, v_6\}$

(20) (a) $v = \begin{bmatrix} 0 \\ b \\ c \end{bmatrix} = b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \Rightarrow W = \text{Span}\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$, these are lin. ind. \Rightarrow they form a basis

b) $\begin{bmatrix} a+c \\ a-b \\ b+c \\ -a+b \end{bmatrix} = a \underset{v_1}{\begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}} + b \underset{v_2}{\begin{bmatrix} 0 \\ -1 \\ 1 \\ 1 \end{bmatrix}} + c \underset{v_3}{\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}} \Rightarrow W = \text{Span}\{v_1, v_2, v_3\}$

To find basis: set $a_1 v_1 + a_2 v_2 + a_3 v_3 = 0 \Rightarrow \begin{bmatrix} 1 & 0 & 1 & | & 0 \\ 1 & -1 & 0 & | & 0 \\ 0 & 1 & 1 & | & 0 \\ -1 & 1 & 0 & | & 0 \end{bmatrix}$

$\xrightarrow{\text{REF}}$ $\begin{bmatrix} 1 & 0 & 1 & | & 0 \\ 0 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \Rightarrow$ Leading 1's give us
 Basis for $W = \{v_1, v_2\}$

(c) $a - b + 5c = 0 \Rightarrow a = b - 5c$

$$\begin{bmatrix} b - 5c \\ b \\ c \end{bmatrix} = b \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} -5 \\ 0 \\ 1 \end{bmatrix}$$

$$\Rightarrow W = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 0 \\ 1 \end{bmatrix} \right\}$$

these are lin. ind. and hence form a basis.

(23) (a) $d = a + b$: $[a \ b \ c \ a+b] = a[1 \ 0 \ 0 \ 1] + b[0 \ 1 \ 0 \ 1] + c[0 \ 0 \ 1 \ 0]$

$$\Rightarrow W = \text{span} \{ [1 \ 0 \ 0 \ 1], [0 \ 1 \ 0 \ 1], [0 \ 0 \ 1 \ 0] \}$$

Check that these are

lin ind. \Rightarrow these vectors form a basis $\Rightarrow \boxed{\dim(W) = 3}$

(b) $c = a - b, d = a + b$

$$[a \ b \ a-b \ a+b] = a[1 \ 0 \ 1 \ 1] + b[0 \ 1 \ -1 \ 1]$$

$$\Rightarrow W = \text{span} \{ \underset{v_1}{[1 \ 0 \ 1 \ 1]}, \underset{v_2}{[0 \ 1 \ -1 \ 1]} \}$$

lin. ind \Rightarrow basis of W

$\Rightarrow \boxed{\dim(W) = 2}$

(29) Standard basis for P_3 is $\{t^3, t^2, t, 1\}$ To find a

basis of P_3 containing $\{t^3+t, t^2-t\}$, consider the set

$$S = \{ \underset{v_1}{t^3+t}, \underset{v_2}{t^2-t}, \underset{v_3}{t^3}, \underset{v_4}{t^2}, \underset{v_5}{t}, \underset{v_6}{1} \}$$

we want to find basis of $\text{span}(S)$

$$a_1 v_1 + a_2 v_2 + a_3 v_3 + a_4 v_4 + a_5 v_5 + a_6 v_6 = 0 \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

REF $\Rightarrow \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$

leading \Rightarrow Basis for P_3 is $\boxed{\{t^3+t, t^2-t, t^3, 1\}}$

(35) let $S = \{v_1, v_2, \dots, v_k\}$ & $T = \{cv_1, v_2, \dots, v_k\}$ $c \neq 0$

We know that S is a basis. To show that T is a basis

(i) $\text{span}(T) = V$: let v be any vector in V . Since S is a basis

we can write $v = a_1 v_1 + a_2 v_2 + \dots + a_k v_k$
 $= \frac{a_1}{c} (cv_1) + a_2 v_2 + \dots + a_k v_k$ (since $c \neq 0$, we can divide by c)

$\Rightarrow v$ lies in $\text{span}(T)$

$\Rightarrow V = \text{span}(T)$

(ii) T is lin ind: If $a_1 (cv_1) + a_2 v_2 + a_3 v_3 + \dots + a_k v_k = 0$

$\Rightarrow (a_1 c) v_1 + a_2 v_2 + \dots + a_k v_k = 0$

Since S is lin. ind we get $a_1 c = 0, a_2 = 0, \dots, a_k = 0$

Since $c \neq 0 \Rightarrow a_1 = 0, a_2 = 0, \dots, a_k = 0 \Rightarrow T$ is lin. ind.

This tells us that T is also a basis for V .

Section 4.4

q) (a) $A = \begin{bmatrix} 1 & 2 & 3 & 2 & 1 \\ 3 & 1 & -5 & -2 & 1 \\ 7 & 8 & -1 & 2 & 5 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 2 & 3 & 2 & 1 \\ 0 & 1 & 14/5 & 8/5 & 2/5 \\ 0 & 0 & 1 & 4/13 & -1/13 \end{bmatrix}$ 3 non-zero rows
 $\Rightarrow \text{Row Rank}(A) = 3$

$A^T = \begin{bmatrix} 1 & 3 & 7 \\ 2 & 1 & 8 \\ 3 & -5 & -1 \\ 2 & -2 & 2 \\ 1 & 1 & 5 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 3 & 7 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ 3 non-zero rows
 $\Rightarrow \text{Row Rank}(A^T) = \text{Column Rank}(A) = 3$.

$$(9)(b) \quad A = \begin{bmatrix} 1 & 3 & 2 & 0 & 0 & 1 \\ 2 & 1 & -5 & 1 & 2 & 0 \\ 3 & 2 & 5 & 1 & -2 & 1 \\ 5 & 8 & 9 & 1 & -2 & 2 \\ 9 & 9 & 4 & 2 & 0 & 2 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 2/7 & 0 \\ 0 & 0 & 1 & 0 & -3/7 & 0 \\ 0 & 0 & 0 & 1 & -3/7 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

5 non-zero rows \Rightarrow Row Rank (A) = 5

$$A^T = \begin{bmatrix} 1 & 2 & 3 & 5 & 9 \\ 3 & 1 & 2 & 8 & 9 \\ 2 & -5 & 5 & 9 & 4 \\ 0 & 1 & 1 & 1 & 2 \\ 0 & 2 & -2 & -2 & 0 \\ 1 & 0 & 1 & 2 & 2 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

5 non-zero rows \Rightarrow Row Rank (\bar{A}) = Column Rank (A) = 5

$$(12)(b) \quad A = \begin{bmatrix} 1 & -2 & -1 \\ 2 & -1 & 3 \\ 7 & -8 & 3 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & -2 & -1 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{Row Rank (A)} = 2$$

$$A^T = \begin{bmatrix} 1 & 2 & 7 \\ -2 & -1 & -8 \\ -1 & 3 & 3 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 2 & 7 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{Column Rank (A)} = 2$$

This verifies Row Rank (A) = Column Rank (A)

$$(13)(b) \quad A = \begin{bmatrix} 1 & 2 & 0 & 3 \\ 3 & 2 & -1 & 0 \\ 2 & -1 & 0 & 1 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 5 \end{bmatrix} \Rightarrow \text{Row Rank (A)} = 3$$

$$A^T = \begin{bmatrix} 1 & 3 & 2 \\ 2 & 2 & -1 \\ 0 & -1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{Column Rank (A)} = 3$$

This verifies Row Rank (A) = Column Rank (A).

$$(14)(a) \quad A = \begin{bmatrix} 1 & 3 & -2 & 4 \\ -1 & 4 & -5 & 10 \\ 3 & 2 & 1 & -2 \\ 3 & -5 & 8 & -16 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 3 & -2 & 4 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{RowRank}(A) = 2$$

$$A^T = \begin{bmatrix} 1 & -1 & 3 & 3 \\ 3 & 4 & 2 & -5 \\ -2 & -5 & 1 & 8 \\ 4 & 10 & -2 & -16 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & -1 & 3 & 3 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{ColumnRank}(A) = 2$$

This verifies that $\text{RowRank}(A) = \text{ColumnRank}(A)$.

$$(26) \quad A = \begin{bmatrix} 1 & 2 & -2 \\ 0 & 8 & -7 \\ 3 & -2 & 1 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 2 & -2 \\ 0 & 1 & -7/8 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \text{Rank}(A) = 3$$

Cor 4.10 says that $A_{n \times n} \underline{x} = \underline{b}$ has a unique solⁿ for any \underline{b} if $\text{Rank}(A) = n$. We showed that $\text{Rank}(A) = 3$ and hence Corollary 4.10 $\Rightarrow A\underline{x} = \underline{b}$ has a unique solⁿ for any \underline{b} .

(34) (a) A 3×4 matrix $\text{Max Rank} = \text{smaller of } 3 \text{ \& } 4 = 3$

(b) A 4×6 matrix
 $\text{Max Rank} = 4$
 Column space spanned by 6 columns but $\dim \leq 4$
 \Rightarrow the columns must be lin. dep.

"
 $\text{Max column} = 4$
 Rank

$\text{Max Rank} = 3$
 (= Max Row Rank)

Row space spanned by 5 rows but $\dim \leq 3 \Rightarrow$ the rows must be lin. ind.

(c) A , 5×3 matrix

(37) $S = \{v_1, v_2, \dots, v_n\}$ n vectors in \mathbb{R}^n 37

A is $n \times n$ matrix with j^{th} row \underline{v}_j .

If S is lin. ind $\Rightarrow \dim(\text{row space}) = n \Rightarrow \text{row rank}(A) = \text{rank}(A) = n$

If $\text{rank}(A) = n \Rightarrow \text{row rank}(A) = n \Rightarrow \dim(\text{row space}) = n$

$\Rightarrow \dim(\text{span}(S)) = n \Rightarrow S$ is lin. ind since S has exactly n vectors.