

FINITE PROPAGATION SPEED AND KERNEL ESTIMATES FOR SCHRÖDINGER OPERATORS

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ABSTRACT. I point out finite propagation speed phenomena for discrete and continuous Schrödinger operators and discuss various types of kernel estimates from this point of view.

1. INTRODUCTION

In this note, I will point out finite propagation speed phenomena associated with continuous Schrödinger operators

$$(1.1) \quad (Hu)(x) = -\Delta u(x) + V(x)u(x)$$

on $L_2(\mathbb{R}^d)$ and their discrete analogs

$$(1.2) \quad (Hu)(n) = \sum_{|m-n|_1=1} u(m) + V(n)u(n),$$

acting on $\ell_2(\mathbb{Z}^d)$. I believe that these observations lead to a very transparent, non-technical and elegant treatment of various topics.

It is instructive to look at the one-dimensional half line problems for a moment. So, consider the operators from (1.1) and (1.2), acting on $L_2(0, \infty)$ and $\ell_2(\mathbb{N})$, respectively. Let ρ be the standard spectral measure; it can be obtained from the Weyl circle construction (see, for example, [4]). Then, in the discrete case, the moments $\int \lambda^n d\rho(\lambda)$ are a very important object, and experience has shown that a similar role is played by the function

$$\phi(t) = \int \cos t\sqrt{\lambda} d\rho(\lambda) - 2\delta(t)$$

in the continuous case. (It can be shown that this formula, suitably interpreted, indeed defines an absolutely continuous function. See, for example, [12].) In other words, there seems to be something special about the functions λ^n and $\cos t\sqrt{\lambda}$, respectively. As we will see in Sect. 2, the unifying theme is *finite propagation speed*, and this in fact works in any dimension.

We will illustrate our basic observations (see Lemmas 2.1, 2.2 below) further by using them to discuss the following two problems:

1. Let f be a bounded smooth function on the spectrum of H . Try to estimate $\langle \varphi_1, f(H)\varphi_2 \rangle$ in terms of the separation of the supports of φ_1 and φ_2 .

2. Suppose that V is known on $B_R(0) = \{x \in \mathbb{R}^d : |x| < R\}$ and φ is supported near zero. What can one then say about $\langle \varphi, f(H)\varphi \rangle$?

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Both problems have been studied before by other methods, the first one in fact quite extensively (see [1] and the references cited therein). The sample results we will prove in Sections 3, 4 below are quite similar to what had been known before. Actually, Corollary 5.3 below does seem to improve results from [1], but that is definitely not my main point in this context. Rather, what I'm trying to emphasize here is the realization that finite propagation speed phenomena are at the heart of the matter, and things become very transparent if this point of view is adopted. This basic idea might be useful in other situations too.

A piece of closely related work is [2], where finite propagation speed methods are used to estimate kernels of functions of the Laplace-Beltrami operator on Riemannian manifolds. In [16], these techniques are used to estimate heat kernels. Finally, see [6, 13] for work on problem 2, and it may also be interesting to take a look at [9] or [11, Sect. XI.11] for the use of wave phenomena in scattering theory.

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2. FINITE PROPAGATION SPEED

We make the following **basic assumptions**: In the continuous case, we assume that H is essentially self-adjoint on $C_0^\infty(\mathbb{R}^d)$ and bounded below. A popular sufficient condition for this is $V \in L_{2,loc}$ and $V_- \in K_d$, the Kato class (V_- denotes the negative part of V). See [17, Sect. 3]. Conversely, the fact that $C_0^\infty(\mathbb{R}^d)$ functions are in the domain of H implies that $V \in L_{2,loc}$.

In the discrete case, we assume that V is bounded. It is then of course automatic that H generates a bounded, self-adjoint operator on $\ell_2(\mathbb{Z}^d)$.

Let us begin with the discrete case. Here the basic lemma is extremely simple.

Lemma 2.1 (finite propagation speed – discrete case). *Consider the operator H from (1.2).*

(a) *Let $\varphi_1, \varphi_2 \in \ell_2(\mathbb{Z}^d)$, and let R be the distance, measured in the $|\cdot|_1$ norm on \mathbb{Z}^d , between the supports of φ_1 and φ_2 . Then*

$$\langle \varphi_1, H^n \varphi_2 \rangle = 0 \quad \text{for } n = 0, 1, \dots, R - 1.$$

(b) *Consider two (bounded) potentials V_1, V_2 and the corresponding Schrödinger operators H_1, H_2 , let $\varphi \in \ell_2(\mathbb{Z}^d)$, and, similarly to the definition in part (a), let*

$$R = \text{dist}(\text{supp } \varphi, \text{supp } (V_1 - V_2)).$$

Then

$$\langle \varphi, H_1^n \varphi \rangle = \langle \varphi, H_2^n \varphi \rangle \quad \text{for } n = 0, 1, \dots, 2R.$$

Proof. It is clear from the form of H that the support of $H\psi$ is contained in a 1-neighborhood (in the $|\cdot|_1$ norm) of the support of ψ . Repeatedly applying this gives (a).

It also follows that in the situation of part (b), $H_1^n \varphi = H_2^n \varphi$ for $n \leq R$ since of course $H_1\psi$ can only be different from $H_2\psi$ if ψ is non-zero at one of the points where $V_1 \neq V_2$. Now it may happen that $(H_1^{R+1}\varphi)(x) \neq (H_2^{R+1}\varphi)(x)$ for some $x \in \mathbb{Z}^d$, but, according to what has just been observed, only at points x from the support of $V_1 - V_2$, and thus it takes at least R more steps to get back to the support of φ (formally, we could in fact apply part (a) to see this). \square

By the spectral theorem, part (b) also says that

$$\int_{\mathbb{R}} \lambda^n d\rho_1(\lambda) = \int_{\mathbb{R}} \lambda^n d\rho_2(\lambda)$$

for $n = 0, 1, \dots, 2R$. Here, ρ_j is the spectral measure for H_j and φ . As already discussed in the Introduction, the appropriate continuous substitutes for the powers λ^n seem to be the functions $\cos t\sqrt{\lambda}$, at least for one-dimensional problems. See also [13] for further background information.

This suggests the following continuous analog of Lemma 2.1. Since we are assuming that H from (1.1) is bounded below, $\cos t\sqrt{\lambda}$ is a bounded function on the spectrum of H . Also, this function clearly does not depend on a choice of the square root and is in fact entire in λ .

Lemma 2.2 (finite propagation speed – continuous case). *Consider the operator H from (1.1).*

(a) *Let $\varphi_1, \varphi_2 \in L_2(\mathbb{R}^d)$ and define*

$$R = \text{dist}(\text{supp } \varphi_1, \text{supp } \varphi_2).$$

Then

$$\langle \varphi_1, \cos t\sqrt{H} \varphi_2 \rangle = 0 \quad \text{for } |t| \leq R.$$

(b) *Consider two potentials V_1, V_2 , let $\varphi \in L_2(\mathbb{R}^d)$ and define*

$$R = \text{dist}(\text{supp } \varphi, \text{supp } (V_1 - V_2)).$$

Then

$$\langle \varphi, \cos t\sqrt{H_1} \varphi \rangle = \langle \varphi, \cos t\sqrt{H_2} \varphi \rangle \quad \text{for } |t| \leq 2R.$$

Proof. By a routine approximation argument, we may and will assume that all functions V and φ are in $C_0^\infty(\mathbb{R}^d)$. Indeed, since the operators $\cos t\sqrt{H}$ are bounded, we can certainly approximate the φ 's in $L_2(\mathbb{R}^d)$ by smooth functions, and we then have convergence of the scalar products we are interested in. We then pick $V_n \in C_0^\infty(\mathbb{R}^d)$ so that $H_n = -\Delta + V_n \rightarrow H$ in strong resolvent sense. This is possible by [10, Theorem VIII.25(a)]. But then also $\cos t\sqrt{H_n} \rightarrow \cos t\sqrt{H}$ strongly, by [10, Theorem VIII.20(b)]. Finally, we can do these approximations in such a way that $\liminf R_n \geq R$ for the separations R defined in the Lemma.

Now let $u = \cos t\sqrt{H} \varphi_2$. Then u solves

$$u_{tt} = -Hu, \quad u(0) = \varphi_2, \quad u_t(0) = 0.$$

Originally, this needs to be interpreted as an equation for functions of t taking values in $L_2(\mathbb{R}^d)$, but V and φ are smooth now, so the regularity results for weak solutions of (generalized) wave equations actually show that $u \in C^\infty(\mathbb{R}^d \times \mathbb{R})$ and

$$(2.1) \quad u_{tt}(x, t) - \Delta u(x, t) = -V(x)u(x, t)$$

holds pointwise. Compare [5, Theorem 7.2.7].

We now need the following classical fact.

Lemma 2.3 (finite propagation speed – wave equation). *Suppose $u \in C^\infty$ solves (2.1) and $u(x, 0) = u_t(x, 0) = 0$ for $|x - x_0| < r$. Then $u \equiv 0$ on $|x - x_0| \leq r - |t|$.*

Proof of Lemma 2.3. We will use an energy estimate. We can assume that u is real valued and $x_0 = 0$. Define

$$E(t) = \int_{B(r-t)} \left(u^2 + u_t^2 + |\nabla u|^2 \right) dx;$$

here, $B(q) = \{x \in \mathbb{R}^d : |x| < q\}$ denotes the ball of radius q . Also, let $S(q)$ be the sphere $S(q) = \{x : |x| = q\}$, and write σ for the surface measure on $S(q)$. We will now compute E' :

$$E' = - \int_{S(r-t)} (u^2 + u_t^2 + |\nabla u|^2) d\sigma + 2 \int_{B(r-t)} (uu_t + u_t u_{tt} + \nabla u \cdot \nabla u_t) dx$$

An integration by parts and use of (2.1) allow us to write the second integral in the form

$$2 \int_{B(r-t)} (1 - V) uu_t dx + 2 \int_{S(r-t)} u_t \mathbf{n} \cdot \nabla u d\sigma,$$

where \mathbf{n} is the outer normal unit vector on the sphere. By the Cauchy-Schwarz inequality, the last term can be estimated by

$$2 \left(\int_{S(r-t)} u_t^2 d\sigma \right)^{1/2} \left(\int_{S(r-t)} |\nabla u|^2 d\sigma \right)^{1/2}.$$

Putting things together, we thus see that

$$E' \leq 2 \int_{B(r-t)} (1 + |V|) |uu_t| dx.$$

Now V is bounded, so a final application of the Cauchy-Schwarz inequality shows that

$$E' \leq C \left(\int_{B(r-t)} u^2 dx \right)^{1/2} \left(\int_{B(r-t)} u_t^2 dx \right)^{1/2} \leq CE.$$

Since $E(0) = 0$, Gronwall's Lemma implies that $E \equiv 0$. This proves the claim (for $t > 0$, but $u(x, -t)$ satisfies the same equation). \square

Part (a) of Lemma 2.2 now follows easily: If x_0 is an arbitrary point from the support of φ_1 , then, by assumption, $\varphi_2(x) = 0$ for all $|x - x_0| < R$. Lemma 2.3 thus shows that $(\cos t\sqrt{H}\varphi_2)(x) = 0$ if $|x - x_0| \leq R - |t|$. In particular, $(\cos t\sqrt{H}\varphi_2)(x_0) = 0$ for $|t| \leq R$. Since $x_0 \in \text{supp } \varphi_1$ was arbitrary, it follows that $\langle \varphi_1, \cos t\sqrt{H}\varphi_2 \rangle = 0$ for these t , as claimed.

To prove part (b), let $u_j = \cos t\sqrt{H_j}\varphi$. The argument is similar to the proof of Lemma 2.1(b): It takes T units of time to reach points where $V_1 \neq V_2$ (starting from the support of φ), and then another time span T to get back to the support of φ . To write this down more formally, first note that Lemma 2.3 shows that $u_j(x, t) = 0$ whenever $\text{dist}(x, \text{supp } \varphi) > |t|$. This shows that for $|t| \leq R$, the difference function $u = u_2 - u_1$ solves

$$(2.2) \quad u_{tt} - \Delta u = -V_1 u$$

for all $x \in \mathbb{R}^d$. Indeed, if $\text{dist}(x, \text{supp } \varphi) < R$, (2.2) follows from the fact that then $V_1(x) = V_2(x)$, and if $\text{dist}(x, \text{supp } \varphi) > R$, then, as we have just seen, $u_1(x, t) = u_2(x, t) = 0$ for $|t| \leq R$.

Since $u(0) = u_t(0) = 0$, Lemma 2.3, applied to (2.2), shows that $u \equiv 0$ for $|t| \leq R$. As argued above, if $\text{dist}(x, \text{supp } \varphi) < R$, then (2.2) in fact holds for all t , so a final application of Lemma 2.3 (to $u(t \pm R)$) shows that $u(t) = 0$ on the support of φ for $|t| \leq 2R$, as desired. \square

3. DECAY OF KERNELS

We begin our discussion of applications of Lemmas 2.1, 2.2 with the first problem mentioned in the Introduction, and we first deal with the discrete case. We will use the following classical result from approximation theory:

Theorem 3.1 (Jackson). *Let $f \in C^\infty[-1, 1]$. Then for every $n \in \mathbb{N}$ and $R \geq n$, there exist polynomials p_R , $\deg p_R \leq R$, so that*

$$\|f - p_R\|_\infty \leq \|f^{(n+1)}\|_1 \left(\frac{5}{R+1} \right)^n.$$

See [3, Sect. 4.6] or [14, Sect. 1.1] for quick proofs (the second reference has bigger constants) and [18] for a more comprehensive discussion of these issues, including optimal results. To obtain the result in the form stated above, use the inequality

$$(3.1) \quad N(N-1)\cdots(N-k+1) \geq \left(\frac{N}{e} \right)^k$$

and note that the modulus of continuity of a function g , defined as $\omega(g, \delta) = \sup_{|x-y|\leq\delta} |g(x) - g(y)|$, can obviously be estimated by $\omega(g, \delta) \leq \|g'\|_1$ if g is differentiable. To prove (3.1), one can use a version of Stirling's formula for $n!$ with explicit error estimates, or simply estimate the logarithm of the left-hand side:

$$\sum_{n=N-k+1}^N \ln n \geq \int_{N-k}^N \ln x \, dx = N \ln N - (N-k) \ln(N-k) - k \geq k(\ln N - 1),$$

as claimed.

We'll use the following notation: For $x \in \mathbb{Z}^d$, let δ_x be the unit vector located at x (so $\delta_x(x) = 1$, $\delta_x(y) = 0$ if $y \neq x$). Moreover, $\sigma(H)$ denotes, as usual, the spectrum of H . The estimates we are about to prove will depend on the diameter of the spectrum.

Theorem 3.2. *Suppose that $\sigma(H) \subset [a, b]$ and $f \in C^\infty[a, b]$. Then, for $n = 1, 2, \dots, |x-y|_1 - 1$,*

$$|\langle \delta_x, f(H)\delta_y \rangle| \leq \|f^{(n+1)}\|_{L_1(a,b)} \left(\frac{5(b-a)}{2|x-y|_1} \right)^n.$$

Proof. Given Lemma 2.1, the proof is straightforward: Let

$$s = \frac{2\lambda - a - b}{b - a}, \quad g(s) = f\left(\frac{a+b}{2} + \frac{b-a}{2}s\right),$$

and approximate g on $[-1, 1]$ by a polynomial of degree $\leq R-1$, with $R \equiv |x-y|_1$:

$$g(s) = p_{R-1}(s) + e_{R-1}(s), \quad -1 \leq s \leq 1$$

By Lemma 2.1(a),

$$\left\langle \delta_x, p_{R-1}\left(\frac{2H - a - b}{b - a}\right) \delta_y \right\rangle = 0,$$

hence

$$|\langle \delta_x, f(H)\delta_y \rangle| \leq \max_{-1 \leq s \leq 1} |e_{R-1}(s)|.$$

By Theorem 3.1, p_{R-1} can be chosen so that

$$|e_{R-1}(s)| \leq \left(\frac{5}{R} \right)^n \|g^{(n+1)}\|_{L_1(-1,1)}.$$

Since $\|g^{(n+1)}\|_{L_1(-1,1)} = \left(\frac{b-a}{2}\right)^n \|f^{(n+1)}\|_{L_1(a,b)}$, the asserted estimate follows. \square

The discussion of the continuous case proceeds along similar lines. We will find it convenient to assume that $H \geq 0$, where now H is the continuous Schrödinger operator from (1.1); the general case (H semibounded below) can of course be reduced to this situation by adding a suitable constant to H (respectively V).

Theorem 3.3. *Assume that $H \geq 0$. Let $f \in C^\infty[0,\infty)$, $\varphi_1, \varphi_2 \in L_2(\mathbb{R}^d)$, and define*

$$R = \text{dist}(\text{supp } \varphi_1, \text{supp } \varphi_2).$$

Also, let $g(k) = f(k^2)$ and assume that $g^{(n)} \in L_1(0,\infty)$ for all $n \geq 0$. Then, for each $n \in \mathbb{N}$, we have that

$$|\langle \varphi_1, f(H)\varphi_2 \rangle| \leq \frac{2\|\varphi_1\| \|\varphi_2\|}{\pi n} \frac{\|g^{(n+1)}\|_{L_1(0,\infty)}}{R^n}.$$

Proof. Expand f in terms of the cosine functions from Lemma 2.2:

$$\begin{aligned} f(\lambda) &= \int_0^\infty \tilde{f}(t) \cos t\sqrt{\lambda} dt, \\ \tilde{f}(t) &= \frac{1}{\pi} \int_0^\infty f(\lambda) \cos t\sqrt{\lambda} \frac{d\lambda}{\sqrt{\lambda}}. \end{aligned}$$

Since $g \in L_1$ or, equivalently, $f \in L_1((0,\infty), d\lambda/\sqrt{\lambda})$, the formula for \tilde{f} in fact holds *pointwise*. (The general theory only guarantees equality in L_2 sense.) Making the substitution $k = \sqrt{\lambda}$, we can write this as

$$\tilde{f}(t) = \frac{2}{\pi} \int_0^\infty g(k) \cos tk dk = \frac{1}{\pi} \int_{-\infty}^\infty g(k) e^{itk} dk,$$

where we have extended g in the obvious way to all of \mathbb{R} . An inductive argument shows that then $g \in C^\infty(\mathbb{R})$ (the only issue being existence of the derivatives at zero). We may now integrate by parts $n+1$ times, and since $g^{(j)} \in L_1$ for all j , there are no boundary terms. Thus

$$(3.2) \quad \left| \tilde{f}(t) \right| \leq \frac{1}{\pi t^{n+1}} \|g^{(n+1)}\|_{L_1(\mathbb{R})} = \frac{2}{\pi t^{n+1}} \|g^{(n+1)}\|_{L_1(0,\infty)}.$$

Now break up f as

$$f(\lambda) = \int_0^R \tilde{f}(t) \cos t\sqrt{\lambda} dt + \int_R^\infty \tilde{f}(t) \cos t\sqrt{\lambda} dt \equiv h(\lambda) + e(\lambda).$$

Again, the rapid decay of \tilde{f} ensures that everything holds pointwise for $\lambda \geq 0$. Moreover, writing $\rho(M) = \langle \varphi_1, E(M)\varphi_2 \rangle$ for the spectral measure of H and φ_1, φ_2 , we have that

$$\langle \varphi_1, h(H)\varphi_2 \rangle = \int_0^R dt \tilde{f}(t) \int d\rho(\lambda) \cos t\sqrt{\lambda} = 0,$$

by Fubini's Theorem and Lemma 2.2(a). Therefore,

$$|\langle \varphi_1, f(H)\varphi_2 \rangle| \leq \|\varphi_1\| \|\varphi_2\| \sup_{\lambda \geq 0} |e(\lambda)|.$$

But the definition of the error term e and (3.2) imply that

$$|e(\lambda)| \leq \int_R^\infty \left| \tilde{f}(t) \right| dt \leq \frac{2}{\pi n R^n} \|g^{(n+1)}\|_{L_1(0,\infty)},$$

and the proof is complete. \square

It is tempting to try to minimize over n in the bounds from Theorems 3.2, 3.3. This can certainly be done if one places some restrictions on the growth of the L_1 norms of the derivatives. We will pursue this theme in Sect. 5, where we will also compare Theorem 3.3 to the closely related work of Bouclet, Germinet, and Klein [1, 7]. These references use the Helffer-Sjöstrand formula and a Combes-Thomas estimate as their main tools.

4. A PRIORI ESTIMATES ON SPECTRAL MEASURES

In a similar way, part (b) of Lemmas 2.1 and 2.2, respectively, yields results addressing the second problem mentioned above. This section is inspired by recent work of Germinet, Kiselev, and Tcheremchantsev [6, Lemma A.1]. We will take a look at this from the point of view suggested by the material of Sect. 2. The treatment of [6] is again based on the Helffer-Sjöstrand formula and a Combes-Thomas estimate. In the one-dimensional case, I earlier discussed related problems in [13] from a point of view remotely reminiscent of the one taken here.

As in the previous section, we begin with the discrete case.

Theorem 4.1. *Let $\varphi \in \ell_2(\mathbb{Z}^d)$, and let V_1, V_2 be two bounded potentials that agree on an R -neighborhood (with respect to the $|\cdot|_1$ norm on \mathbb{Z}^d) of the support of φ . Determine an interval $[a, b] \supset \sigma(H_1) \cup \sigma(H_2)$ and let $f \in C^\infty[a, b]$. Then, for $n = 1, 2, \dots, 2R$,*

$$|\langle \varphi, f(H_1)\varphi \rangle - \langle \varphi, f(H_2)\varphi \rangle| \leq 2\|\varphi\|^2 \|f^{(n+1)}\|_{L_1(a,b)} \left(\frac{5(b-a)}{4R} \right)^n.$$

For an interesting application, let f approximate the characteristic function of an interval I . Since $\langle \varphi, f(H_j)\varphi \rangle = \int f(\lambda) d\rho_j(\lambda)$, where ρ_j is the spectral measure of H_j and φ , Theorem 4.1 now says that it is possible to approximately compute $\rho(I)$ for an interval $I \subset \mathbb{R}$ with high accuracy, provided V is known on an R -neighborhood of $\text{supp } \varphi$ and $R|I| \gg 1$ (because $\|f^{(n+1)}\|_1 \sim |I|^{-n}$ for typical approximations f). See [8, Sect. 8] for such an application of [6, Lemma A.1].

Proof. Let again

$$s = \frac{2\lambda - a - b}{b - a}, \quad g(s) = f\left(\frac{a+b}{2} + \frac{b-a}{2}s\right),$$

and write, according to Theorem 3.1,

$$g(s) = p_{2R}(s) + e_{2R}(s), \quad -1 \leq s \leq 1,$$

with a polynomial p_{2R} of degree $\leq 2R$. By Lemma 2.1(b),

$$\left\langle \varphi, p_{2R}\left(\frac{2H_1 - a - b}{b - a}\right) \varphi \right\rangle = \left\langle \varphi, p_{2R}\left(\frac{2H_2 - a - b}{b - a}\right) \varphi \right\rangle.$$

As in the previous section, $\|g^{(n+1)}\|_1 = \left(\frac{b-a}{2}\right)^n \|f^{(n+1)}\|_1$, so Theorem 3.1 shows that for $-1 \leq s \leq 1$,

$$|e_{2R}(s)| \leq \left(\frac{5(b-a)}{4R}\right)^n \|f^{(n+1)}\|_1,$$

and the asserted inequality follows. \square

Let us now discuss the continuous case. We will again assume that $H_j \geq 0$, which, of course, is just a normalization. Also, as noted in the previous section, the more natural variable is $k = \sqrt{\lambda}$ and thus our result reads as follows:

Theorem 4.2. *Let $f \in C_0^\infty[0, \infty)$, and define $g(k) = f(k^2)$. Let $\varphi \in L_2(\mathbb{R}^d)$ and suppose that V_1, V_2 agree on an R -neighborhood of the support of φ . Then, for every $n \in \mathbb{N}$,*

$$|\langle \varphi, f(H_1)\varphi \rangle - \langle \varphi, f(H_2)\varphi \rangle| \leq \frac{4\|\varphi\|^2 \|g^{(n+1)}\|_{L_1(0,\infty)}}{n\pi(2R)^n}.$$

Proof. The basic ideas are familiar by now, so it will suffice to provide a sketch of the argument. Expand f :

$$\begin{aligned} f(\lambda) &= \int_0^\infty \tilde{f}(t) \cos t\sqrt{\lambda} dt, \\ \tilde{f}(t) &= \frac{1}{\pi} \int_{-\infty}^\infty g(k) e^{itk} dk. \end{aligned}$$

We argue as in the proof of Theorem 3.3. More specifically, write

$$f(\lambda) = \int_0^{2R} \tilde{f}(t) \cos t\sqrt{\lambda} dt + \int_{2R}^\infty \tilde{f}(t) \cos t\sqrt{\lambda} dt \equiv h + e,$$

note that $\langle \varphi, (h(H_1) - h(H_2))\varphi \rangle = 0$ by Lemma 2.2(b), and use (3.2) to bound the error term e . \square

5. SOME REMARKS ON GEVREY TYPE FUNCTIONS

Usually, one defines the class of Gevrey functions on an interval $I \subset \mathbb{R}$ as follows (we restrict to the one-dimensional case right away because that is all we will need here): By definition, $f \in G_s(I)$ if $f \in C^\infty(I)$ and

$$(5.1) \quad |f^{(n)}(x)| \leq C^{n+1} n^{sn} \quad (x \in K, n \in \mathbb{N}_0)$$

for every compact subset $K \subset I$. Here, $s \geq 1$, and the constant C may depend on f and K . The functions $f \in G_1(I)$ are in fact real analytic (see [15, Theorem 19.9]). On the other hand, if $s > 1$, then $G_s(I)$ contains compactly supported functions (easily constructed with the help of the functions $\exp(-x^{-b})$ for suitable $b > 0$).

For our purposes, it is clear from the results discussed in Sect. 3, 4 that *global* control on the derivatives is more relevant. This was also (and previously) recognized in [1]. The following definition seems most appropriate:

Definition 5.1. Let $I \subset \mathbb{R}$ be an interval and let $s \geq 1$. We say that $f \in G_s^1(I)$ if $f \in C^\infty(I)$ and there exists a constant $C > 0$ so that

$$\|f^{(n)}\|_{L_1(I)} \leq C^{n+1} n^{sn} \quad \text{for all } n \in \mathbb{N}_0.$$

The relation of this to G_s can be clarified by making the following quick observations: Suppose that $f \in G_s^1(I)$. Then there exists a constant $A > 0$ (any positive A with $A|I| > 1$ will do), so that for every $n \in \mathbb{N}_0$, we can find an $x_0^{(n)} \in I$ so that

$|f^{(n)}(x_0^{(n)})| \leq AC^{n+1}n^{sn}$. But then for arbitrary $x \in I$, we have that

$$\begin{aligned} |f^{(n)}(x)| &\leq |f^{(n)}(x_0^{(n)})| + \|f^{(n+1)}\|_{L_1(I)} \leq AC^{n+1}n^{sn} + C^{n+2}(n+1)^{s(n+1)} \\ &= C^{n+1}n^{sn} \left(A + C(n+1)^s \left(1 + \frac{1}{n} \right)^{sn} \right). \end{aligned}$$

It follows that there exists a new constant D , independent of n , so that $|f^{(n)}(x)| \leq D^{n+1}n^{sn}$ on I . In particular, $f \in G_s(I)$, but we have in fact obtained the stronger statement that the constants C from (5.1) can be taken to be independent of K . We denote the set of functions satisfying such a uniform Gevrey condition by $G_s^{\text{unif}}(I)$. Also, it is obvious, by integrating the pointwise bounds, that $G_s(K) \subset G_s^1(K)$ for compact intervals $K \subset \mathbb{R}$. We have thus proved the following.

Proposition 5.1. (a) $G_s^1(I) \subset G_s^{\text{unif}}(I) \subset G_s(I)$;
(b) $G_s^1(K) = G_s(K)$ if $K \subset \mathbb{R}$ is a compact interval.

If our functions are in G_s^1 , we can obtain more explicit information from the results of the preceding sections. We illustrate this with the Gevrey versions of Theorems 3.2 and 3.3, respectively. Of course, there are similar Gevreyizations of Theorems 4.1 and 4.2, which we won't make explicit.

Corollary 5.2. In the situation of Theorem 3.2, suppose that $f \in G_s^1[a, b]$. Then there exist constants $C, \gamma > 0$ so that

$$|\langle \delta_x, f(H)\delta_y \rangle| \leq C \exp(-\gamma|x - y|_1^{1/s}).$$

Proof. It suffices to take $n \approx (R/C)^{1/s}$ with a suitable constant C in Theorem 3.2. To spell this out more explicitly, first note that by Theorem 3.2 and the definition of G_s^1 , we have that

$$(5.2) \quad |\langle \delta_x, f(H)\delta_y \rangle| \leq \left(\frac{Bn^s}{R} \right)^n \quad (n \in \mathbb{N}, R \equiv |x - y|_1 > n)$$

for a suitable constant $B > 0$. We may assume that $B \geq 2/e$, and we then pick n so that

$$\frac{R}{2eB} \leq n^s \leq \frac{R}{eB},$$

provided there actually exists an integer satisfying these bounds. This, however, will certainly be the case if R is large enough. Since $s \geq 1$, n is then not larger than $R - 1$, and thus (5.2) shows that

$$|\langle \delta_x, f(H)\delta_y \rangle| \leq e^{-n} \leq e^{-\gamma R^{1/s}}.$$

This proves the asserted bound for large R , and validity for all R is then achieved by simply adjusting the constant C . \square

As observed above in Proposition 5.1(b), $G_s^1[a, b] = G_s[a, b]$, so we don't really need Definition 5.1 here. The class G_s^1 does become relevant, however, in the continuous case because then the spectra are unbounded and global bounds are needed. We have the following analog of Corollary 5.2.

Corollary 5.3. In the situation of Theorem 3.3, suppose that $g \in G_s^1([0, \infty))$. Then there exist constants $C, \gamma > 0$ so that

$$|\langle \varphi_1, f(H)\varphi_2 \rangle| \leq C \|\varphi_1\| \|\varphi_2\| \exp(-\gamma R^{1/s}).$$

The *proof* is completely analogous to the proof of Corollary 5.2. \square

In [1], Bouclet, Germinet, and Klein introduce the class of $C^\infty(I)$ functions f that obey estimates of the form

$$\int_I (1 + |\lambda|)^{n-1} |f^{(n)}(\lambda)| d\lambda \leq C^{n+1} n^{sn},$$

and they go on to prove that if this holds on an open interval I containing the spectrum of H , then

$$|\langle \varphi_1, f(H)\varphi_2 \rangle| \lesssim \exp(-\gamma R^{(1/s)-\epsilon})$$

for every $\epsilon > 0$ [1, Theorem 1.4].

It may therefore be interesting to relate our hypothesis that $g \in G_s^1$, where $g(k) = f(k^2)$, to such a condition.

Theorem 5.4. *Let $s \geq 1$. Suppose that $f \in C^\infty[0, \infty)$ and*

$$\int_0^\infty (1 + \lambda)^{(n-1)/2} |f^{(n)}(\lambda)| d\lambda \leq C^{n+1} n^{sn} \quad (n \in \mathbb{N}_0).$$

Then $g(k) = f(k^2) \in G_s^1([0, \infty))$.

Proof. This is elementary but a bit tedious. Working out the derivatives with the help of the chain and product rules, we see that $g^{(n)}$ is of the form

$$g^{(n)}(k) = \sum a_{ij}(n) k^i f^{(j)}(k^2),$$

where the sum ranges over all indices $n/2 \leq j \leq n$, $0 \leq i \leq j$ satisfying $i = 2j - n$. To confirm that this relation between i and j must hold, one can argue as follows: To produce a contribution of the form $k^i f^{(j)}$, we clearly must let precisely j of the n derivatives act on f . By the chain rule, this gives j factors of k , and the remaining $n - j$ derivatives must then act on these. As a result, the exponent j decreases by $n - j$; in other words, $i = 2j - n$. The other restrictions on i, j follow from this.

Our task is to extract some information on the coefficients $a_{ij}(n)$. By taking the derivative in the above representation, it follows that the $a_{ij}(n)$ obey the recursion

$$(5.3) \quad a_{ij}(n) = (i+1)a_{i+1,j}(n-1) + 2a_{i-1,j-1}(n-1).$$

It will be convenient to use the difference $d = j - i$ as the parameter indexing the coefficients a . Note that for fixed n , we have that $0 \leq d \leq n/2$. Moreover, $a_{ij}(n)$ can be different from zero only if $i = n - 2d$, $j = n - d$. We'll use the abbreviation $C_d(n) = a_{n-2d,n-d}(n)$, and we then claim that

$$(5.4) \quad 0 \leq C_d(n) \leq \frac{2^{n-2d} n^{2d}}{d!}.$$

Of course, only the upper bound needs proof, and we can use induction on d . The case $d = 0$ corresponds to letting all the derivatives act on f , so $C_0(n) = 2^n$. Now assume that (5.4) holds for $d - 1$, with $d \geq 1$. By (5.3) and the definition of $C_d(n)$,

$$C_d(n) = (n - 2d + 1)C_{d-1}(n-1) + 2C_d(n-1).$$

We will now iterate this, using the induction hypothesis and the fact that $d \geq 1$ to estimate the first term on the right-hand side. In the first step, we obtain

$$\begin{aligned} C_d(n) &\leq \frac{2^{n-2d+1}}{(d-1)!} (n-1)^{2d-1} + 2C_d(n-1) \\ &= \frac{2^{n-2d+1}}{(d-1)!} (n-1)^{2d-1} + 2((n-1)-2d+1)C_{d-1}(n-2) + 2^2C_d(n-2) \\ &\leq \frac{2^{n-2d+1}}{(d-1)!} ((n-1)^{2d-1} + (n-2)^{2d-1}) + 2^2C_d(n-2). \end{aligned}$$

Continuing in this way and recalling that $C_d(n) = 0$ as soon as $n < 2d$, we see that

$$C_d(n) \leq \frac{2^{n-2d+1}}{(d-1)!} \sum_{j=1}^{n-1} j^{2d-1} \leq \frac{2^{n-2d+1}}{(d-1)!} \int_1^n x^{2d-1} dx < \frac{2^{n-2d} n^{2d}}{d!},$$

as required.

We are now ready to estimate the integrals $\int_0^\infty |g^{(n)}| dk$. To prove Theorem 5.4, it clearly suffices to show that

$$C_d(n) \int_0^\infty k^{n-2d} \left| f^{(n-d)}(k^2) \right| dk \leq C^{n+1} n^{sn}$$

for $0 \leq d \leq n/2$, with a constant C independent of d and n . We will split these integrals into two parts, corresponding to $0 \leq k \leq 1$ and $k > 1$, respectively. Consider first $C_d(n) \int_1^\infty \dots$. Using $\lambda = k^2$ as the variable, we can write this as

$$\frac{1}{2} C_d(n) \int_1^\infty \lambda^{(n-2d-1)/2} \left| f^{(n-d)}(\lambda) \right| d\lambda,$$

and, by hypothesis, we have a bound of the form $C_d(n) C^{n+1} (n-d)^{s(n-d)}$. So, taking (5.4) into account, we must now show that there exists a constant $C > 0$ so that

$$\frac{n^{2d}}{d^d} (n-d)^{s(n-d)} \leq C^{n+1} n^{sn}$$

for all $0 \leq d \leq n/2$. This can be done quite easily, by simply further estimating $(n-d)^{s(n-d)} \leq n^{s(n-d)}$.

A similar argument lets us bound $C_d(n) \int_0^1 \dots$. We can in fact work with pointwise bounds. Indeed, by hypothesis and Proposition 5.1(b), $f \in G_s[0, 1]$, so, reasoning along the above lines, we see that $g \in G_s[0, 1]$, too. \square

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