13.2: Derivatives and Integrals of Vector Functions

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Overview

In the previous section we defined the concept of a vector function (i.e. a function that takes a real number and returns a vector), and learned that the graphs of such functions in \mathbb{R}^3 are space curves. Therefore, the calculus of space curves in \mathbb{R}^3 amounts to the calculus of these vector functions.

We began moving toward this calculus by defining the limit of a vector function. We now continue in that vein, and cover the fundamentals of the calculus of space curves: derivatives and integrals.

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The Derivative

Let $\vec{r}(t)$ be a vector-valued function. Its **derivative** is defined as follows:

$$\frac{\mathrm{d}\,\vec{r}}{\mathrm{d}t}=\vec{r}'(t)=\lim_{h\to 0}\frac{\vec{r}(t+h)-\vec{r}(t)}{h}$$

Note that this is analogous to the definition of the derivative of a single-variable real-valued function f(x). In fact, one can show that directly from this definition that if $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ with f, g, and h differentiable, then

$$\vec{r}'(t) = \left\langle f'(t), g'(t), h'(t) \right\rangle$$

Calculate the derivative of $\vec{r}(t) = \left< 1 + t^3, te^{-t}, \sin(2t) \right>$ at t = 0.

From the previous slide, we have:

$$\vec{r}'(t) = \left\langle \frac{\mathrm{d}}{\mathrm{d}t} (1+t^3), \frac{\mathrm{d}}{\mathrm{d}t} (te^{-t}), \frac{\mathrm{d}}{\mathrm{d}t} \sin(2t) \right\rangle$$
$$= \left\langle 3t^2, e^{-t} - te^{-t}, 2\cos(2t) \right\rangle$$

Thus, plugging in t = 0, we have:

$$\vec{r}'(0) = \langle 0, 1, 2 \rangle$$

Graphical Interpretation

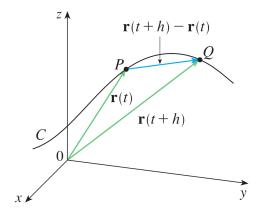
Given a real-valued function f(x), we know that the derivative of f at x = a represents the slope of the line tangent to f at the point (a, f(a)). What can we say about the derivative of a vector-valued function $\vec{r}(t)$?

Graphical Interpretation, cont.

Recall that for a vector function $\vec{r}(t)$, we have:

$$\vec{r}'(t) = \lim_{h \to 0} \frac{\vec{r}(t+h) - \vec{r}(t)}{h}$$

Consider the following sketch of *C*, the graph of $\vec{r}(t)$:



Graphical Interpretation, cont.

As *h* approaches 0, the point *Q* in the previous slide approaches the point *P*, and thus the secant vector $\vec{r}(t+h) - \vec{r}(t)$ approaches a vector tangent to *C* at *P*. Multiplying by $\frac{1}{h}$ only scales the secant vector in this process, and thus:

 $\vec{r}'(t)$ represents a vector tangent to the graph of $\vec{r}(t)$ at a given t

Find a vector \vec{w} that lies tangent to the graph of the vector function $\vec{r}(t) = \langle 1 + t^3, te^{-t}, \sin(2t) \rangle$ at the point (1, 0, 0).

From the previous slide, we know that one such vector is the derivative of $\vec{r}(t)$ at the point (1,0,0). So, the first thing we need to know is when the graph of $\vec{r}(t)$ passes through the point (1,0,0), i.e., what *t*-value(s) give $\vec{r}(t) = \langle 1 + t^3, te^{-t}, \sin(2t) \rangle = \langle 1, 0, 0 \rangle$. Well, from the first components of each we see that $1 + t^3 = 1$ gives t = 0. A quick calculation verifies that $\vec{r}(0) = \langle 1, 0, 0 \rangle$.

Therefore, a vector tangent to the graph of $\vec{r}(t)$ at the point (1,0,0) is:

$$\vec{w} = \vec{r}'(0) = \left\langle 3t^2, e^{-t} - te^{-t}, 2\cos(2t) \right\rangle \Big|_{t=0} = \boxed{\langle 0, 1, 2 \rangle}$$

The Unit Tangent Vector

For calculations, we will sometimes want the tangent vector to have unit length (i.e. length 1), so we construct the **unit tangent vector**:

$$ec{T}(t) \coloneqq rac{ec{r}'(t)}{\left|ec{r}'(t)
ight|}$$

First, notice that this vector is also tangent to the graph of $\vec{r}(t)$, as it is a scalar multiple of $\vec{r}'(t)$. Furthermore, it has length 1, as:

$$\left|\vec{T}(t)\right| = \left|\frac{\vec{r}'(t)}{\left|\vec{r}'(t)\right|}\right| = \frac{\left|\vec{r}'(t)\right|}{\left|\vec{r}'(t)\right|} = 1$$

Find a unit vector \vec{u} that lies tangent to graph of $\vec{r}(t) = \langle 1 + t^3, te^{-t}, \sin(2t) \rangle$ at the point (1, 0, 0).

In the previous example, we saw that a vector tangent to $\vec{r}(t)$ at the point (1,0,0) is $\vec{r}'(0) = \langle 0,1,2 \rangle$. So, a *unit* tangent vector is:

$$\vec{u} = \frac{\vec{r}'(0)}{\left|\vec{r}'(0)\right|} = \frac{\langle 0, 1, 2 \rangle}{\left|\langle 0, 1, 2 \rangle\right|} = \frac{\langle 0, 1, 2 \rangle}{\sqrt{0^2 + 1^2 + 2^2}} = \left\lfloor \left\langle 0, \frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}} \right\rangle \right\rfloor$$

Connection to Slope and the Tangent Line

In single-variable calculus, the derivative f'(a) of a function f(x) at x = a gives the slope of the line tangent to the graph of f(x) at the point (a, f(a)). Using this information, we can then give an equation for this tangent line.

Here we have a similar situation: the derivative $\vec{r}'(a)$ of $\vec{r}(t)$ at t = a gives a vector tangent to the graph of $\vec{r}(t)$ at the point corresponding to $\vec{r}(a)$. This tangent vector can be thought of as a direction vector of the line tangent to the graph of $\vec{r}(t)$ at t = a.

Give a set of parametric equations for the line *L* that lies tangent to the graph of $\vec{r}(t) = \langle 1 + t^3, te^{-t}, \sin(2t) \rangle$ at the point (1, 0, 0).

We know from the first example above that a vector tangent to the graph of $\vec{r}(t)$ at the point (1,0,0) is (0,1,2). Therefore, a direction vector for *L* is (0,1,2). Furthermore, a point on *L* is (1,0,0). Thus, by our work in section 12.5, a set of parametric equations for *L* is:

$$\begin{aligned} x(t) &= 1\\ y(t) &= t\\ z(t) &= 2t \end{aligned}$$

Differentiation Rules

Just as with real-valued functions, there are several differentiation rules that may come in handy. Let $\vec{u}(t)$ and $\vec{v}(t)$ be differentiable vector functions, let *c* be a scalar, and let f(t) be a real-valued function. We have:

1.
$$\frac{d}{dt} (\vec{u}(t) + \vec{v}(t)) = \vec{u}'(t) + \vec{v}'(t)$$

2.
$$\frac{d}{dt} (c\vec{u}(t)) = c\vec{u}'(t)$$

3.
$$\frac{d}{dt} (f(t)\vec{u}(t)) = f'(t)\vec{u}(t) + f(t)\vec{u}'(t)$$

4.
$$\frac{d}{dt} (\vec{u}(t) \cdot \vec{v}(t)) = \vec{u}'(t) \cdot \vec{v}(t) + \vec{u}(t) \cdot \vec{v}'(t)$$

5.
$$\frac{d}{dt} (\vec{u}(t) \times \vec{v}(t)) = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$$

6.
$$\frac{d}{dt} [\vec{u}(f(t))] = f'(t)\vec{u}'(f(t))$$

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Definition

The **definite integral** of a continuous vector function $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ is defined analogously to the definite integral of a continuous real function, as follows:

$$\int_{a}^{b} \vec{r}(t) dt = \lim_{n \to \infty} \sum_{i=1}^{n} \vec{r}(t_{i}) \Delta t$$
$$= \lim_{n \to \infty} \left\langle \sum_{i=1}^{n} f(t_{i}) \Delta t, \sum_{i=1}^{n} g(t_{i}) \Delta t, \sum_{i=1}^{n} h(t_{i}) \Delta t \right\rangle$$
$$= \left\langle \int_{a}^{b} f(t) dt, \int_{a}^{b} g(t) dt, \int_{a}^{b} h(t) dt \right\rangle$$

Unlike the derivative, there is no nice graphical interpretation of the definite integral of a vector function.

The Fundamental Theorem

Let $\vec{R}(t)$ be an antiderivative for $\vec{r}(t)$. Then, by the previous slide, the Fundamental Theorem of Calculus carries over for vector functions, and says:

$$\int_{a}^{b} \vec{r}(t) dt = \vec{R}(t) \Big|_{a}^{b} = \vec{R}(b) - \vec{R}(a)$$

Let
$$\vec{r}(t) = \langle 2\cos(t), \sin(t), 2t \rangle$$
. Evaluate $\int_0^{\pi/2} \vec{r}(t) dt$.

By the fundamental theorem, we have:

$$\int_{0}^{\pi/2} \vec{r}(t) dt = \int_{0}^{\pi/2} \langle 2\cos(t), \sin(t), 2t \rangle dt$$
$$= \left\langle 2\sin(t), -\cos(t), t^{2} \right\rangle \Big|_{0}^{\pi/2}$$
$$= \left[\left\langle 2, 1, \frac{\pi^{2}}{4} \right\rangle \right]$$

Indefinite Integrals

What about indefinite integrals? Recall that the indefinite integral of a real-valued function is its most general antiderivative. The same is true of vector functions. Let's illustrate this with an example.

Evaluate $\int \langle 2\cos(t), \sin(t), 2t \rangle dt$.

We have:

$$\int \langle 2\cos(t), \sin(t), 2t \rangle dt = \left\langle \int 2\cos(t) dt, \int \sin(t) dt, \int 2t dt \right\rangle$$
$$= \left\langle 2\sin(t) + C_1, -\cos(t) + C_2, t^2 + C_3 \right\rangle$$
$$= \left\langle 2\sin(t), -\cos(t), t^2 \right\rangle + \left\langle C_1, C_2, C_3 \right\rangle$$
$$= \left\langle 2\sin(t), -\cos(t), t^2 \right\rangle + \vec{C}$$

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- 1. Let $\vec{r}(t) = \langle \sqrt{t}, (2-t) \rangle$. Evaluate $\vec{r}'(1)$. Then find $\vec{T}(1)$, the unit tangent vector to $\vec{r}(t)$ at t = 1.
- 2. Let $\vec{r}(t) = \langle 2\cos(t), \sin(t), t \rangle$. Find a set of parametric equations for the line *L* that lies tangent to the graph of $\vec{r}(t)$ at the point $(0, 1, \pi/2)$.
- 3. Evaluate $\int \left\langle \frac{1}{t+1}, \frac{1}{t^2+1}, \frac{t}{t^2+1} \right\rangle dt$ and $\int_0^1 \left\langle \frac{1}{t+1}, \frac{1}{t^2+1}, \frac{t}{t^2+1} \right\rangle dt$.

Solutions

1.
$$\vec{r}'(1) = \left\langle \frac{1}{2}, -1 \right\rangle, \quad \vec{T}(1) = \left\langle \frac{1}{\sqrt{5}}, -\frac{2}{\sqrt{5}} \right\rangle$$

2. [One possible answer:] A set of parametric equations for L is:

$$x = -2t$$
$$y = 1$$
$$z = t + \frac{\pi}{2}$$

3.
$$\int \left\langle \frac{1}{t+1}, \frac{1}{t^2+1}, \frac{t}{t^2+1} \right\rangle dt = \left\langle \ln(t+1), \arctan(t), \frac{1}{2}\ln(t^2+1) \right\rangle + \vec{C};$$

and
$$\int_0^1 \left\langle \frac{1}{t+1}, \frac{1}{t^2+1}, \frac{t}{t^2+1} \right\rangle dt = \left\langle \ln(2), \frac{\pi}{4}, \frac{1}{2}\ln(2) \right\rangle.$$