

**Problem 1.** Directly from the definition, find the rates of convergence  $\alpha$  and the asymptotic error constants  $\lambda$  for each of the sequences (all of which tend to 0)

$$(a) \ p_n = \frac{1}{n^2} ; \quad (b) \ p_n = 7^{-n} ; \quad (c) \ p_n = 10^{-5^n} .$$

**Problem 2.** The concept of rate of convergence (in particular, the order of convergence  $\alpha$  and the asymptotic error constant  $\lambda$ ) are very important when one is using an *iterative method*, i.e., a method in which the exact solution of the problem is found as a limit of a sequence of approximate values. If the exact value  $p$  is a limit of a sequence  $\{p_n\}_{n=0}^{\infty}$  of approximate values, then the *error* at the  $n$ th step of the iteration is  $E_n := |p_n - p|$ . The rate of decreasing of the error is one of the most important characteristics of iterative methods of numerical computations.

Assume that the sequence  $\{p_n\}_{n=0}^{\infty}$  is generated by some iterative method for finding a root of an equation. Also assume that we know that the sequence  $\{p_n\}_{n=0}^{\infty}$  converges to some number  $p$  of some order  $\alpha$  with some asymptotic error constant  $\lambda$ , but we don't know the values of  $\alpha$  and  $\lambda$ . The goal of this problem is to develop a method for determining the numerical value of  $\alpha$  from the numerical values of the members of the sequence  $\{p_n\}_{n=0}^{\infty}$ . Let  $E_n := |p_n - p|$  be the error at the  $n$ th step of the iteration, and define  $\ell_n := \log_{10} E_n$ .

(a) Show that for large  $n$ , the following approximate identity holds:

$$\ell_n - \alpha \ell_{n-1} \approx \log_{10} \lambda .$$

*Hint:* Just look at the definition of order of convergence.

(b) Using the approximate identity derived in (a) show that

$$\alpha \approx \frac{\ell_n - \ell_{n+1}}{\ell_{n-1} - \ell_n} .$$

Note that this approximate formula for  $\alpha$  does not depend on the base of the logarithms; if  $\ell_n$  is defined as the log base 10 of  $E_n$ , the formula will remain the same.

(c) The data in the table below come from applying the so-called *Newton method* and the *secant method* to find the root of the equation

$$x + \sin x = 1 ,$$

whose exact value is  $p = 0.51097342938856910952001397114508063204535889262 \dots$ . Use the formula derived in part (b) to find empirically the order of convergence  $\alpha$  for these two methods.

Table 1:  $\text{Log}_{10}$  of the errors of the Newton and the secant methods.

$n$	$\ell_n$ , Newton	$\ell_n$ , secant
0	-0.31067	-0.31067
1	-2.85988	-1.49389
2	-7.84087	-2.54052
3	-17.7179	-4.90935
4	-37.4715	-8.33484
5	-76.9787	-14.1282
6	-155.993	-23.3471
7	-314.022	-38.3595
8	-630.079	-62.5907
9	-1262.19	-101.834
10	-2526.42	-165.309
11	-5054.88	-268.027
12	-10111.8	-434.220

**Problem 3.** As discussed in class, the polynomials of order no higher than  $n$  form a linear space with respect to the addition of polynomials and multiplication of a polynomial by a number as follows: if  $P$  and  $Q$  are polynomials of degree  $\leq n$  and  $\alpha \in \mathbb{R}$ , then the polynomials  $P + Q$  and  $\alpha P$  are defined as follows:

$$(P + Q)(x) := P(x) + Q(x) , \quad (\alpha P)(x) := \alpha P(x) .$$

Let  $V_n(a, b; w(x))$  stand for the linear space of polynomials defined on the interval with left end  $a$  and right end  $b$  (at each end, the interval can be open or closed;  $a$  and  $b$  can be finite or infinite) of degree no greater than  $n$  endowed with the inner product

$$(P, Q) = \int_a^b P(x) Q(x) w(x) dx .$$

Dana defined a family of polynomials which she denoted (very modestly!) by  $D_0, D_1, D_2, \dots$ . These polynomials satisfy the following conditions:

- (i) the polynomial  $D_k$  is of degree  $k$ ;
- (ii) the coefficient of  $x^k$  in  $D_k$  is equal to 1 (such polynomials are called *monic*, following the definition on page 377 of the book);
- (iii) the polynomials  $D_0, D_1, D_2, \dots, D_n$  form an orthogonal basis in the space of polynomials  $V_n(0, \infty; w(x) = e^{-x})$ .

In the solution of this problem the following identity will be handy:

$$\int_0^{\infty} x^k e^{-x} dx = k!$$

(where, by definition,  $0! = 1$ ).

- (a) Clearly,  $D_0(x) = 1$  for each  $x \in [0, \infty)$ . Find the only monic polynomial  $D_1$  of degree 1 that is orthogonal to  $D_0$ .
- (b) Find the only monic quadratic polynomial  $D_2$  that is orthogonal to both  $D_0$  and  $D_1$ .
- (c) Show that the polynomial  $P(x) = x^2 + 3$  can be represented as a linear combination of the polynomials  $D_0$ ,  $D_1$  and  $D_2$  as follows:  $P = D_2 + 4D_1 + 5D_0$ .
- (d) Show by direct integration that  $(D_0, D_0) = 1$ ,  $(D_1, D_1) = 1$ ,  $(D_2, D_2) = 4$ .

- (e) Find the orthogonal projection,  $\text{proj}_{D_0+2D_1} P$ , of the polynomial  $P(x) = x^2 + 3$  onto the “straight line”

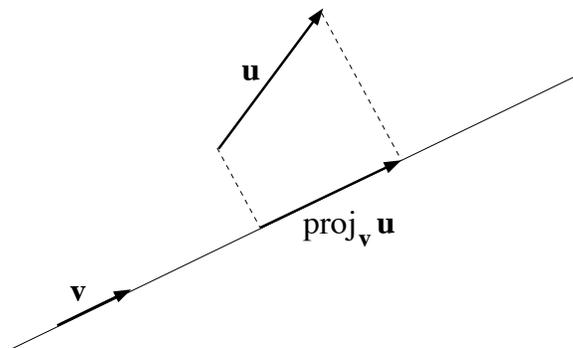
$$\ell := \{t(D_0 + 2D_1) \mid t \in \mathbb{R}\}$$

in the 3-dimensional inner product linear space  $V_2(0, \infty; e^{-x})$ . If you have solved part (c), then finding this orthogonal projection should be easy.

*Hint:* If  $\mathbf{u}$  and  $\mathbf{v}$  are vectors in the inner product linear space  $V$ , then the orthogonal projection of the vector  $\mathbf{u}$  onto the straight line in the direction of  $\mathbf{v}$  is the vector

$$\text{proj}_{\mathbf{v}} \mathbf{u} = \frac{(\mathbf{u}, \mathbf{v})}{(\mathbf{v}, \mathbf{v})} \mathbf{v}$$

– see the picture below.



- (f) Finally, let  $\tilde{D}_k := \mu_k D_k$ , where  $\mu_k > 0$  is a constant (depending on  $k$ ) such that the norm,

$$\|\tilde{D}_k\| := \sqrt{(\tilde{D}_k, \tilde{D}_k)},$$

of the polynomial  $\tilde{D}_k$  is 1. Find the explicit expressions for  $\tilde{D}_0(x)$ ,  $\tilde{D}_1(x)$ , and  $\tilde{D}_2(x)$ .

**Problem 4.** Hilbert matrices are a family of matrices that have very high condition numbers. The Hilbert matrix  $H^{(n)}$  of size  $n \times n$  has matrix elements

$$h_{ij}^{(n)} = \frac{1}{i+j-1}.$$

The MATLAB command to generate a Hilbert matrix of size  $\mathbf{n}$  is `hilb(n)`. In this problem you will use MATLAB to study the reliability of the residual and the relative residual as a predictor of the error of an approximate solution of the linear system  $H^{(11)}\mathbf{x} = \mathbf{b}$ .

- (a) In MATLAB, let  $\mathbf{A}$  denote the Hilbert matrix  $H^{(11)}$ , and `xexact` stand for the exact solution  $\mathbf{x}_{\text{exact}} = (1 \ 2 \ 3 \ \dots \ 10 \ 11)^T$ . Define the right-hand side  $\mathbf{b}$  by typing `b = A*xexact`, and then let `xapprox` be the solution of the linear system  $H^{(11)}\mathbf{x} = \mathbf{b}$  found by MATLAB (you can find `xapprox` by using the MATLAB command `inv` to invert the matrix  $\mathbf{A}$ , no need to write your own program).
- (b) Find the error  $\mathbf{e} = \mathbf{x}_{\text{approx}} - \mathbf{x}_{\text{exact}}$  and the residual  $\mathbf{r} = H^{(11)}\mathbf{x}_{\text{approx}} - \mathbf{b}$ , and the  $\ell_\infty$ -norms of  $\mathbf{b}$ ,  $\mathbf{x}_{\text{exact}}$ ,  $\mathbf{e}$ , and  $\mathbf{r}$ , as well as the relative error and the relative residual.
- (c) Use the MATLAB command `norm` to find  $\|H^{(11)}\|_\infty$ ,  $\|(H^{(11)})^{-1}\|_\infty$ , and  $\kappa_\infty(H^{(11)})$ .
- (d) Check that all inequalities proved in the Theorem on page 182 of the book hold in the particular example in this problem. Please write a clear and detailed solution.