

Problem 1. Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a C^∞ function (i.e., a function that is differentiable infinitely many times), and suppose that $x \in \mathbb{R}$ and $h > 0$ are some fixed numbers. Derive a formula to approximate $f'(x)$ that uses only $f(x-2h)$, $f(x)$, $f(x+h)$, $f(x+3h)$ such that the local truncation error is $O(h^3)$, i.e., such that

$$f'(x) = [\text{your expression approximating } f'(x)] + O(h^3) .$$

Hint: Expand $f(x-2h)$, $f(x+h)$, $f(x+3h)$ in a Taylor series about x up to h^3 , as in

$$f(x+h) = f(x) + f'(x)h + \frac{1}{2!}f''(x)h^2 + \frac{1}{3!}f'''(x)h^3 + O(h^4) ,$$

and from these expressions eliminate the terms containing $f''(x)$ and $f'''(x)$.

Problem 2. The quadrature formula

$$\int_0^2 f(x) dx = c_0 f(0) + c_1 f(1) + c_2 f(2)$$

is exact for all polynomials of degree less than or equal to 2. Determine c_0 , c_1 , and c_2 .

Hint: Note that this quadrature formula must be exact for the polynomials $f(x) = 1$, $f(x) = x$, and $f(x) = x^2$. Use this fact to write a system of three (linear) equations for c_0 , c_1 , and c_2 .

Problem 3. Bhagyashri defined a family of polynomials, which she modestly denoted by B_0 , B_1 , B_2 , \dots , that satisfy the following conditions:

- (i) the polynomial B_k is of degree k ;
- (ii) the polynomials B_k are *monic*, i.e., the coefficient in front of the term with the highest power of x in B_k (in our case, this is the coefficient of x^k) is equal to 1;
- (iii) the polynomials B_0 , B_1 , B_2 , \dots , B_n form an orthogonal basis in the space of polynomials $V_n(0, \infty; w(x) = e^{-x})$.

Recall that $V_n(a, b; w(x))$ stands for the linear space of polynomials of degree no greater than n endowed with the inner product

$$\langle P, Q \rangle = \int_a^b P(x) Q(x) w(x) dx .$$

In the solution of this problem the following identity will be handy (where $0! := 1$):

$$\int_0^\infty x^k e^{-x} dx = k! .$$

- (a) Clearly, $B_0(x) = 1$ for each $x \in [0, \infty)$. Find the only monic polynomial B_1 of degree 1 that is orthogonal to B_0 .
- (b) Find the only monic quadratic polynomial B_2 that is orthogonal to both B_0 and B_1 .
- (c) Show that the polynomial $P(x) = x^2 + 3$ can be represented as a linear combination of the polynomials B_0, B_1 and B_2 as follows: $P = B_2 + 4B_1 + 5B_0$.
- (d) Show directly that $\langle B_0, B_0 \rangle = 1$, $\langle B_1, B_1 \rangle = 1$, $\langle B_2, B_2 \rangle = 4$.
- (e) Find the orthogonal projection, $\text{proj}_{B_0+2B_1} P$, of the polynomial $P(x) = x^2 + 3$ onto the “straight line”

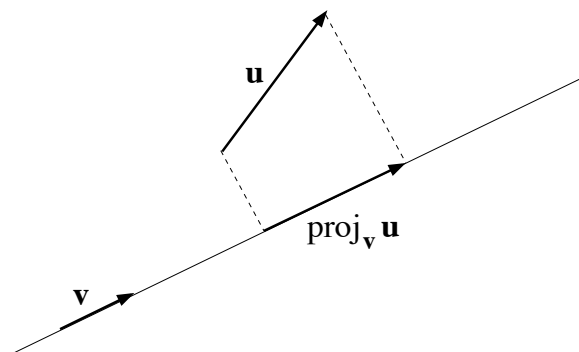
$$\ell := \{t(B_0 + 2B_1) \mid t \in \mathbb{R}\}$$

in the 3-dimensional inner product linear space $V_2(0, \infty; e^{-x})$. If you have solved part (c), then finding this orthogonal projection should be easy.

Hint: If \mathbf{u} and \mathbf{v} are vectors in the inner product linear space V , then the orthogonal projection of the vector \mathbf{u} onto the straight line in the direction of \mathbf{v} is the vector

$$\text{proj}_{\mathbf{v}} \mathbf{u} = \frac{\langle \mathbf{u}, \mathbf{v} \rangle}{\langle \mathbf{v}, \mathbf{v} \rangle} \mathbf{v}$$

– see the picture below.



- (f) Finally, let $\tilde{B}_k := \mu_k B_k$, where $\mu_k > 0$ is a constant (depending on k) such that the norm,

$$\|\tilde{B}_k\| := \sqrt{\langle \tilde{B}_k, \tilde{B}_k \rangle},$$

of the polynomial \tilde{B}_k is 1. Find the explicit expressions for $\tilde{B}_0(x)$, $\tilde{B}_1(x)$, and $\tilde{B}_2(x)$.

Problem 4. The Legendre polynomials are a family of monic polynomials

$$P_0(x) = 1, \quad P_1(x) = x, \quad P_2(x) = x^2 - \frac{1}{3}, \quad P_3(x) = x^3 - \frac{3}{5}x, \dots,$$

such that P_0, P_1, \dots, P_n form an orthogonal basis of the linear space $V_n(-1, 1; w(x) \equiv 1)$ (i.e., the vector space of all polynomials of degree $\leq n$ endowed with the weight function $w(x) = 1$ for all $x \in [-1, 1]$).

The goal of this problem is to find a Gaussian quadrature formula with degree of precision 5 based on the general formalism developed in class. The notations used are the same as in the handout “Theoretical foundations of Gaussian quadrature”.

- (a) Find the roots x_1 , x_2 , and x_3 , of the polynomial P_3 . Order them so that $x_1 < x_2 < x_3$.

Remark: Recall that the general theory (Lemma 1 on page 7 of the handout) guarantees that P_3 has three *real* roots, all of them in the interval $(-1, 1)$.

- (b) Write down the polynomials L_1 , L_2 , L_3 .

Hint: Here is what I obtained for L_2 : $L_2(x) = -\frac{5}{3}x^2 + 1$ (but you have to derive this).

- (c) Find the weights w_1 , w_2 , w_3 .

Hint: I obtained $w_3 = \frac{5}{9}$.

- (d) Write down the quadrature formula coming from parts (a), (b), (c).

- (e) Show that the quadrature formula obtained in (d) is *exact* for all monomials x^k if k is an odd positive integer.

Hint: This can be done without doing any computations!

- (f) Show that the quadrature formula obtained in (d) is exact for the polynomial $f(x) = 1$.

- (g) Show that the quadrature formula obtained in (d) is exact for the polynomial $f(x) = x^2$.

- (h) Show that the quadrature formula obtained in (d) is exact for the polynomial $f(x) = x^4$.

- (i) Show that the quadrature formula obtained in (d) is *not* exact for the polynomial $f(x) = x^6$. Does this agree with the theoretical prediction about the degree of precision of the method you developed?

- (j) Now let us apply the beautiful quadrature formula you derived in (d) to a concrete problem. The so-called *error function* is defined as

$$\operatorname{erf}(z) := \frac{2}{\sqrt{\pi}} \int_0^z e^{-x^2} dx .$$

It is important for engineering applications; it is related to the c.d.f. $\Phi(z)$ of the standard normal distribution by $\operatorname{erf}(z) = 2\Phi(\sqrt{2}z) - 1$. (To solve this problem, you do not need to know what these words mean.)

You have to find the value of $\operatorname{erf}(1)$. Since the limits of the integral in the definition of $\operatorname{erf}(1)$ are 0 and 1 but in the quadrature formula the integral was from -1 to 1 , first find an appropriate *linear* change of variables $y = \eta(x)$ such that $\eta(0) = -1$ and $\eta(1) = 1$. Change the integration variable from x to $y = \eta(x)$.

Remark: You can also find infinitely many nonlinear changes of variables that satisfy these two conditions, but why make things more complicated?

- (k) Apply the Gaussian quadrature formula found in (d) to compute the numerical value of $\operatorname{erf}(1)$. Find the absolute and the relative error if you know that the exact value of $\operatorname{erf}(1)$ is

$$\operatorname{erf}(1)_{\text{exact}} = 0.8427007929497148693412206350826092592960669979663029084599 \dots$$