## $\sigma$ -Fields, Conditional Expectation

**Definition:** Let  $\Omega$  be a set, and let  $\mathcal{F}$  be a  $\sigma$ -field of subsets of  $\Omega$ , i.e., a collection of subsets of  $\Omega$  whose elements satisfy the following properties:

- $(\sigma 1) \emptyset \in \mathcal{F}$  (where  $\emptyset$  is the empty set,  $\emptyset := \{\}$ );
- $(\sigma 2)$  if  $A_1, A_2, \ldots$  are elements of  $\mathcal{F}$ , then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ ;
- $(\sigma 3)$  if  $A \in \mathcal{F}$ , then its complement,  $A^c := \Omega \setminus A$ , belongs to  $\mathcal{F}$ .

**Remark:** In probability language,  $\Omega$  is called the *sample space*, the elements of  $\Omega$  are called *outcomes*, the elements of  $\mathcal{F}$  are called *events*.

**Remark:** Note that  $A \in \mathcal{F}$ , but  $A \subseteq \Omega$ .

**Definition:** We say that the collection  $\mathcal{G}$  of subsets of  $\Omega$  is a *sub-\sigma-field* of  $\mathcal{F}$  (and we write  $\mathcal{G} \subseteq \mathcal{F}$ ) if all elements of  $\mathcal{G}$  are also elements of  $\mathcal{F}$ , and  $\mathcal{G}$  itself is a \sigma-field (i.e., the elements of  $\mathcal{G}$  satisfy the properties  $(\sigma 1)$ - $(\sigma 3)$ ).

**Definition:** Let  $A_1, A_2, \ldots$  be an arbitrary collection of subsets of  $\Omega$ . The smallest  $\sigma$ -field that contains all  $A_1, A_2, \ldots$  can be constructed by taking all possible unions of intersections of  $A_i$ 's or their complements. The notation for this  $\sigma$ -field is  $\sigma(A_1, A_2, \ldots)$ ; we say that  $\sigma(A_1, A_2, \ldots)$  is generated by  $A_1, A_2, \ldots$ 

**Remark:** The smallest  $\sigma$ -field of subsets of  $\Omega$  (notation:  $\sigma(\emptyset)$  or, equivalently,  $\sigma(\Omega)$ ) consists of  $\emptyset$  and  $\Omega$  only; it is a sub- $\sigma$ -field of any other  $\sigma$ -field of subsets of  $\Omega$ .

**Example A:** Let  $\Omega = \{1, 2, 3, 4, 5, 6\}$ , and let  $E := \{2, 4, 6\}$  be the set of all even numbers, while  $F := \{1, 2, 3, 4\}$ . Then

$$\sigma(E) = \{\emptyset, E = \{2, 4, 6\}, E^c = \{1, 3, 5\}, \Omega\} ,$$

$$\sigma(F) = \{\emptyset, F = \{1, 2, 3, 4\}, F^c = \{5, 6\}, \Omega\} ,$$

and  $\sigma(E, F)$  consists of the following 8 sets:

$$\emptyset,\,E=\{2,4,6\},\,E^c=\{1,3,5\},\,EF=\{2,4\},\,EF^c=\{6\},\,E^cF=\{1,3\},\,E^cF^c=\{5\},\,\Omega\ .$$

Note that  $\sigma(E) \subseteq \sigma(E, F)$  and  $\sigma(F) \subseteq \sigma(E, F)$ . Also note that in this example the subset  $\{2\}$  does not belong to  $\sigma(E, F)$ . The largest  $\sigma$ -field of subsets of  $\Omega$  in this example – let us call it  $\mathcal{F}$  – has  $2^6$  elements; can you write them down?

*Hint:* There are  $\binom{6}{0} = 1$  elements of  $\mathcal{F}$  consisting of 0 elements of  $\Omega$ ,  $\binom{6}{1} = 6$  elements

of  $\mathcal{F}$  consisting of 1 element of  $\Omega$ ,  $\binom{6}{2} = 15$  elements of  $\mathcal{F}$  consisting of 2 elements of  $\Omega$ ,  $\binom{6}{3} = 20$  elements of  $\mathcal{F}$  consisting of 3 elements of  $\Omega$ ,  $\binom{6}{4} = 15$  elements of  $\mathcal{F}$  consisting of 4 elements of  $\Omega$ ,  $\binom{6}{5} = 6$  elements of  $\mathcal{F}$  consisting of 5 elements of  $\Omega$ , and  $\binom{6}{6} = 1$  elements of  $\mathcal{F}$  consisting of 6 elements of  $\Omega$ .

**Definition:** A function  $\mathbb{P}: \mathcal{F} \to [0,1]$  is a *probability measure* on  $(\Omega, \mathcal{F})$  if it satisfies the following properties:

$$(\mathbb{P}1) \ \mathbb{P}(\emptyset) = 0, \ \mathbb{P}(\Omega) = 1;$$

(P2) if 
$$A_1, A_2, \ldots$$
 are elements of  $\mathcal{F}$  that are  $disjoint$ , i.e.,  $A_i \cap A_j = \emptyset$  for all  $i \neq j$ , then  $\mathbb{P}\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} \mathbb{P}(A_i)$ .

**Example A (cont.):** Since we have different  $\sigma$ -fields, there are different probabilities. If we know the probability  $\mathbb{P}: \mathcal{F} \to [0,1]$  (where  $\mathcal{F}$  was the largest  $\sigma$ -field of subsets of  $\Omega$ ), then we can construct the probabilities

$$\bar{\mathbb{P}}: \sigma(E) \to [0,1] , \quad \tilde{\mathbb{P}}: \sigma(F) \to [0,1] , \quad \mathbb{P}^*: \sigma(E,F) \to [0,1] , \quad \mathbb{P}^{\dagger}: \sigma(\emptyset) \to [0,1]$$

in such a way that all these probabilities are consistent with P. For example,

$$\tilde{\mathbb{P}}(\emptyset) = 0 \ , \quad \tilde{\mathbb{P}}(F) = \frac{2}{3} \ , \quad \tilde{\mathbb{P}}(F^c) = \frac{1}{3} \ , \quad \tilde{\mathbb{P}}(\Omega) = 1 \ ,$$

while  $\mathbb{P}^{\dagger}(\emptyset) = 0$ ,  $\mathbb{P}^{\dagger}(\Omega) = 1$ . (Note that  $\mathbb{P}^{\dagger}(E)$ , among many other things, is not defined!)

**Definition:** Let  $\mathbb{R}$  be the real line, and let  $\mathcal{B}(\mathbb{R})$  be the  $\sigma$ -field generated by all open sets of  $\mathbb{R}$ ; the  $\sigma$ -field  $\mathcal{B}(\mathbb{R})$  is called the *Borel*  $\sigma$ -field on  $\mathbb{R}$ .

**Definition:** A function  $X : \Omega \to \mathbb{R}$  is called a *random variable* if the preimage of each Borel set in  $\mathbb{R}$  is an element of  $\mathcal{F}$ , i.e., each subset of  $\Omega$  of the form  $X^{-1}(B) := \{\omega \in \Omega : X(\omega) \in B\}$  is an element of  $\mathcal{F}$ , for any Borel set  $B \in \mathcal{B}(\mathbb{R})$ .

**Remark:** The above definition is very simple although it may sound complicated. Think about the discrete case: if X is a function  $X: \Omega \to \{x_1, x_2, \ldots\} \subset \mathbb{R}$  that takes a finite or a countable set of values, then it is a (discrete) random variable if and only if  $X^{-1}(x_i) \in \mathcal{F}$  for all values  $x_i$  that X can possibly take.

**Definition:** The  $\sigma$ -field  $\sigma(X)$  generated by the discrete random variable X is defined as the  $\sigma$ -field generated by all subsets of the form  $X^{-1}(x_i)$  for all possible values  $x_i$  of X.

In general (not only for a discrete random variable),  $\sigma(X)$  is defined as the  $\sigma$ -field generated by the set of  $X^{-1}(B)$  for all  $B \in \mathcal{B}(\mathbb{R})$ .

**Example A (cont.):** Let X, Y, and Z be random variables defined as follows:

$$X(\omega) = \omega \quad \text{for all } \omega \in \Omega ,$$
 
$$Y(\omega) = \begin{cases} 8 & \text{for } \omega \in E = \{2,4,6\} ,\\ 9 & \text{for } \omega \in E^c = \{1,3,5\} , \end{cases}$$
 
$$Z(\omega) = \begin{cases} 10 & \text{for } \omega \in F = \{1,2,3,4\} ,\\ 13 & \text{for } \omega \in F^c = \{5,6\} . \end{cases}$$

Then  $\sigma(X) = \mathcal{F}$  (recall that  $\mathcal{F}$  is the largest  $\sigma$ -field of subsets of  $\Omega$ ),  $\sigma(Y) = \sigma(E)$ , and  $\sigma(Z) = \sigma(F)$ .

If you know that  $Y(\omega) = 9$ , then you know that  $\omega$  is an odd number (i.e., belongs to the set  $Y^{-1}(9) = \{1, 3, 5\} \subset \sigma(Y)$ ), but you do not know the exact value of  $\omega$ .

If, in addition to  $Y(\omega) = 9$ , I tell you that  $Z(\omega) = 10$ , then you can conclude that  $\omega$  must belong to  $Y^{-1}(9) \cap Z^{-1}(10) = \{1, 3\} \subset \sigma(Y, Z)$ , so the new information allowed us to narrow the possible set of values of  $\omega$  (but we are still not sure whether  $\omega$  is 1 or 3). This reasoning leads us to the following

## Very Important Remark (as Winnie the Pooh would say):

If  $X_1, X_2, X_3, \ldots$  is a sequence of random variables on the same probability space, we can construct the  $\sigma$ -fields

$$\mathcal{F}_1 := \sigma(X_1) , \quad \mathcal{F}_2 := \sigma(X_1, X_2) , \quad \mathcal{F}_3 := \sigma(X_1, X_2, X_3) , \quad \dots$$

each of which is clearly a sub- $\sigma$ -field of the next one:

$$\mathcal{F}_1 \subseteq \mathcal{F}_2 \subseteq \mathcal{F}_3 \subseteq \cdots$$
.

Such a nested sequence of  $\sigma$ -fields is sometimes called a *filtration* of  $\sigma$ -fields. For an outcome  $\omega \in \Omega$ , to know  $X_1(\omega)$  is the same as to know to which element of  $\mathcal{F}_1 = \sigma(X_1)$  the outcome  $\omega$  belongs. To know  $X_1(\omega)$  and  $X_2(\omega)$  is the same as knowing to which element of  $\mathcal{F}_2 = \sigma(X_1, X_2)$  the outcome  $\omega$  belongs, etc.

Now think of  $X_n$  as a piece of information about  $\omega$  that you receive at time  $t = n \in \mathbb{N}$ , i.e., at time t = 1 somebody tells us the value of  $X_1(\omega)$ , at time t = 2 somebody tells us the value of  $X_2(\omega)$ , at time t = 3 somebody tells us the value of  $X_3(\omega)$ , etc. Then, obviously, the longer we wait, the more information about  $\omega$  we will acquire, and the more "precisely" we will know it.

As an example of such a situation, think about the following: I will be telling you the consecutive digits of a number  $\omega$  between 0 and 1, one digit per second. If at time t=1, I tell you "5", which means that that  $\omega \in [0.5, 0.6)$ . At time t=2, I tell you "1", and you learn that  $\omega \in [0.51, 0.52)$ . At time t=3, I tell you "7", and you now know that  $\omega \in [0.517, 0.518)$ , etc. Clearly, in the notation introduced above,  $\mathcal{F}_1$  is generated of all sets of the form  $\left[\frac{i}{10^1}, \frac{i+1}{10^1}\right)$  for  $i \in \{0, 1, 2, \dots, 10^1 - 1\}$ ,  $\mathcal{F}_2$  is generated of all sets of the form  $\left[\frac{i}{10^2}, \frac{i+1}{10^2}\right)$  for  $i \in \{0, 1, 2, \dots, 10^2 - 1\}$ , etc.

A subset  $A \subseteq \Omega$  belongs to the  $\sigma$ -field  $\mathcal{F}_n$  if and only if the knowledge of the values  $X_1(\omega)$ ,  $X_2(\omega), \ldots, X_n(\omega)$  will allow you to determine whether  $\omega \in A$  or  $\omega \notin A$  for an arbitrary  $\omega \in \Omega$ .

**Example:** For the situation just considered, let A be the event

 $A := \{ \text{there are at least two digits 4 among the first five digits of the number } \omega \}$ .

("Digits" here means "digits to the right of the decimal point".)

To which  $\mathcal{F}_n$  does the event A belong? In general, to be able to answer this question, we have to know the first five digits of  $\omega$ , which tells us that  $A \in \mathcal{F}_5$ , and, since  $\mathcal{F}_5 \subseteq \mathcal{F}_6 \subseteq \mathcal{F}_7 \subseteq \cdots$ , we have that  $A \in \mathcal{F}_n$  for all  $n \geq 5$ . It may happen that for some particular  $\omega$  we can determine whether  $\omega$  belongs to A even before we know all the 5 first digits of  $\omega$  – for example, if it happens that  $X_1(\omega) = 4$  and  $X_2(\omega) = 4$ , then we would know that  $\omega \in A$ . This, however, does not imply that  $A \in \mathcal{F}_2$  – think about the case  $X_1(\omega) = 1$ ,  $X_2(\omega) = 4$ ,  $X_1(\omega) = 3$ ,  $X_4(\omega) = 7$  – can you say whether there are two digits 4 in the first five digits of  $\omega$  before you learn  $X_5(\omega)$ ? Clearly not.

Once again, note that since the event A belongs to  $\mathcal{F}_5$ , it belongs to all events  $\mathcal{F}_n$  with  $n \geq 5$ . As an exercise, for each of the following events find the smallest n such that the event belongs to  $\mathcal{F}_n$ :

- $B := \{ \text{the first occurrence of the digit 7 in } \omega \text{ is preceded by no more than ten digits 2} \};$
- $C := \{ \text{there is at least one digit 0 among the digits of } \omega \};$
- $D := \{ \text{the first one hundred digits of } \omega \text{ are the same} \};$
- $E := \{ \text{there are no more than two digits 4 and two digits } \neq 4 \text{ among the first five digits of } \omega \}.$

Answers:  $B \in \mathcal{F}_{11}$  but does not belong to  $\mathcal{F}_{10}$ ; C does not belong to  $\mathcal{F}_n$  for any  $n \in \mathbb{N}$ ;  $D \in \mathcal{F}_{100}$  but not to  $\mathcal{F}_{99}$ ;  $E \in \mathcal{F}_n$  for all  $n \in \mathbb{N}$  because  $E = \emptyset$ , and the empty set belongs to all  $\mathcal{F}_n$ .

**Definition:** Let  $X_n$  be a sequence of a random variables on the probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , and let

$$\mathcal{F}_1 \subseteq \mathcal{F}_2 \subseteq \mathcal{F}_3 \subseteq \cdots$$

be a filtration of sub- $\sigma$ -fields of  $\mathcal{F}$ , where  $\mathcal{F}_n = \sigma(X_1, X_2, \ldots, X_n)$ . Let  $S_n$  be a sequence of random variables on the same probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . We say that the sequence  $S_n$  is adapted to the filtration  $\mathcal{F}_n$  if we can find the value of  $S_n(\omega)$  from the values of  $X_1(\omega)$ ,  $X_2(\omega)$ , ...,  $X_n(\omega)$  (in a more mathematical language, the sequence  $S_n$  is adapted to the filtration  $\mathcal{F}_n$  if  $S_n$  is  $\mathcal{F}_n$ -measurable).

**Example:** Let  $S_n := X_1 + X_2 + \cdots + X_n$  be the random variable equal to the sum of the first n digits of the random number  $\omega \in [0,1)$ . Then  $S_n(\omega) = \sum_{i=1}^n X_i(\omega)$ , i.e., if we know

 $X_1(\omega), X_2(\omega), \ldots, X_n(\omega)$ , we will be able to find  $S_n(\omega)$ . This means that the sequence of random variables  $S_n$  is adapted to the filtration  $\mathcal{F}_n$ , where  $\mathcal{F}_n = \sigma(X_1, \ldots, X_n)$ .

**Definition:** Let  $\mathbb{E}(Y|X=x)$  be the average value of X over all elements of  $X^{-1}(x)$ :

$$\mathbb{E}(Y|X=x) := \sum_{y} y \, f_{Y|X}(y|x) = \sum_{y} y \, \mathbb{P}(Y=y|X=x) = \sum_{x} x \, \frac{\mathbb{P}(Y=y,X=x)}{\mathbb{P}(X=x)} \ .$$

We define the *conditional expectation*,  $\mathbb{E}(Y|X)$ , of Y given X as a random variable  $\mathbb{E}(Y|X)$ :  $\Omega \to \mathbb{R}$  such that

$$\mathbb{E}(Y|X)(\omega) = \mathbb{E}(Y|X = X(\omega)) = \sum_{y} y f_{Y|X}(y|X(\omega)) ,$$

i.e.,  $\mathbb{E}(Y|X)(\omega)$  is the average of Y over the event  $X^{-1}(X(\omega))$ .

**Remark:** Note that if  $X(\omega) = X(\omega')$ , then  $\mathbb{E}(Y|X)(\omega) = \mathbb{E}(Y|X)(\omega')$ . This means that  $\mathbb{E}(Y|X)$  – which is a random variable on the sample space  $\Omega$  endowed with the  $\sigma$ -field  $\mathcal{F}$  – can also be considered as a random variable on the sample space  $\Omega$  endowed with the  $\sigma$ -field  $\sigma(X)$  (which obviously is a sub- $\sigma$ -field of  $\mathcal{F}$ ).

**Remark:** Convince yourself that the discrete random variables X and  $\mathbb{E}(Y|X)$  can be written as

$$X = \sum_{x} x \, I_{X^{-1}(x)} , \qquad \mathbb{E}(Y|X) = \sum_{x} \mathbb{E}(Y|X = x) \, I_{X^{-1}(x)} .$$

This can be interpreted as the fact that  $\mathbb{E}(Y|X)$  is a function of X,  $\mathbb{E}(Y|X) = \psi(X)$  for some (Borel-measurable) function  $\psi : \mathbb{R} \to \mathbb{R}$ :

$$\mathbb{E}(Y|X)(\omega) = \psi(X(\omega)) .$$

Remark: Recall that the event  $X^{-1}(X(\omega)) = \{\omega' \in \Omega : X(\omega') = X(\omega)\}$  is an element of the  $\sigma$ -field  $\sigma(X)$  generated by the random variable X. Note that the value of  $\mathbb{E}(Y|X)(\omega)$  does not depend on the numerical value of  $X(\omega)$ , but only on the element  $X^{-1}(X(\omega))$  of the  $\sigma(X)$  to which  $\omega$  belongs. This means that instead of  $\mathbb{E}(Y|X)$ , we can write  $\mathbb{E}(Y|\sigma(X))$ . Now recall that in the Very Important Remark above we constructed a sequence of nested  $\sigma$ -fields  $\mathcal{F}_1 \subseteq \mathcal{F}_2 \subseteq \mathcal{F}_3 \subseteq \cdots$  generated by the sequence of random variables  $X_1, X_2, X_3, \ldots$ , where  $\mathcal{F}_n = \sigma(X_1, \ldots, X_n)$ . Taking into account what we have just discussed, we introduce the notation (which is standard in the theory of martingales)

$$\mathbb{E}(Y|\mathcal{F}_n) := \mathbb{E}(Y|\sigma(X_1,\ldots,X_n)) .$$

If  $X_1(\omega) = x_1, \ldots, X_n(\omega) = x_n$ , then the value of  $\mathbb{E}(Y|\mathcal{F}_n)(\omega)$  is equal to the average of Y over the event  $\{X_1 = x_1\} \cap \cdots \cap \{X_n = x_n\}$ .

**Example A (cont.):** Show that  $\mathbb{E}(X) = 3.5$ ,  $\mathbb{E}(Y) = 8.5$ ,  $\mathbb{E}(Z) = 11$ , while for the conditional expectations we have

$$\mathbb{E}(X|Y)(\omega) = \mathbb{E}(X|Y=8) = 2 \cdot \frac{1}{3} + 4 \cdot \frac{1}{3} + 6 \cdot \frac{1}{3} = 4 \quad \text{for } \omega \in Y^{-1}(8) = \{2,4,6\} \ ,$$

$$\mathbb{E}(X|Y)(\omega) = \mathbb{E}(X|Y=9) = 1 \cdot \frac{1}{3} + 3 \cdot \frac{1}{3} + 5 \cdot \frac{1}{3} = 3 \quad \text{for } \omega \in Y^{-1}(9) = \{1,3,5\} \ ;$$

$$\mathbb{E}(X|Z)(\omega) = \mathbb{E}(X|Z=10) = 1 \cdot \frac{1}{4} + 2 \cdot \frac{1}{4} + 3 \cdot \frac{1}{4} + 4 \cdot \frac{1}{4} = 2.5 \quad \text{for } \omega \in Z^{-1}(10) = \{1,2,3,4\} \ ,$$

$$\mathbb{E}(X|Z)(\omega) = \mathbb{E}(X|Z=13) = 5 \cdot \frac{1}{2} + 6 \cdot \frac{1}{2} = 5.5 \quad \text{for } \omega \in Z^{-1}(13) = \{5,6\} \ .$$

Now we compute the expectation of the random variables  $\mathbb{E}(X|Y)$  and  $\mathbb{E}(X|Z)$ :

$$\mathbb{E}\left[\mathbb{E}(X|Y)\right] = \sum_{y=8,9} \mathbb{E}(X|Y=y) \,\mathbb{P}(Y=y) = 4 \cdot \frac{1}{2} + 3 \cdot \frac{1}{2} = 3.5 ,$$

$$\mathbb{E}\left[\mathbb{E}(X|Z)\right] = \sum_{z=10,13} \mathbb{E}(X|Z=z) \, \mathbb{P}(Z=z) = 2.5 \cdot \frac{2}{3} + 5.5 \cdot \frac{1}{3} = 3.5 \ ,$$

and notice that  $\mathbb{E}[\mathbb{E}(X|Y)] = \mathbb{E}(X)$  and  $\mathbb{E}[\mathbb{E}(X|Z)] = \mathbb{E}(X)$ , as it should, according to Theorem 3.7.6. As an exercise, show that:

- $\mathbb{E}(Y|X)(\omega) = 8 \text{ for } \omega \in \{2,4,6\}, \ \mathbb{E}(Y|X)(\omega) = 9 \text{ for } \omega \in \{1,3,5\}, \ \mathbb{E}\left[\mathbb{E}(Y|X)\right] = 8.5;$
- $\mathbb{E}(Y|Z)(\omega) = 8.5 \text{ for } \omega \in \Omega, \mathbb{E}\left[\mathbb{E}(Y|Z)\right] = 8.5;$
- $\mathbb{E}(Z|X)(\omega) = 10$  for  $\omega \in \{1, 2, 3, 4\}$ ,  $\mathbb{E}(Z|X)(\omega) = 13$  for  $\omega \in \{5, 6\}$ ,  $\mathbb{E}[\mathbb{E}(Z|X)] = 11$ ;
- $\mathbb{E}(Z|Y)(\omega) = 11$  for  $\omega \in \Omega$ ,  $\mathbb{E}\left[\mathbb{E}(Z|Y)\right] = 11$ .